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Spallation Neutron Source

Ring DI Water System Controls Functional System Design (FSD)

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APPROVED
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SPALLATION NEUTRON SOURCE

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Ring DI Water System Controls Description TD8019 Rev 0

Operating Philosophy

Purpose:

The purpose of DI water system operation is to:

- a) Maintain the DI water at an appropriate temperature setpoint.
- b) Provide alarms if the resistivity in the circulating loop or polishing loop are abnormal

Assumptions: Running both pumps simultaneously is not acceptable.

Operator Controls and Operating Modes

- 1) OFF: Pumps are de-energized. Tower water return line control valve at 50% open.
- 2) PUMP A IS PRIMARY: Pump A is energized and pump B is de-energized.
- 3) PUMP B IS PRIMARY: Pump B is energized and pump A is de-energized

OPERATOR INTERFACE DEFINITIONS

Local Hardware/Manual Operator Controls

- 1) Post heat exchanger DI water pressure (*PI 4600A, PI 4601A, PI 4602A, PI 4700A, PI 4400A, PI 4800A*)
- 2) Pre heat exchanger DI water pressure (*PI 4600B, PI 4601B, PI 4602B, PI 4700B, PI 4400B, PI 4800B*)
- 3) Filter skid DI water pressure #1 (*PI 4600E, PI 4601E, PI 4602E, PI 4700E, PI 4400E, PI 4800E*)
- 4) Filter skid DI water pressure #2 (*PI 4600F, PI 4601F, PI 4602F, PI 4700F, PI 4400F, PI 4800F*)
- 5) Filter skid DI water pressure #3 (*PI 4600G, PI 4601G, PI 4602G, PI 4700G, PI 4400G, PI 4800G*)
- 6) Post heat exchanger DI water temperature (*TI 4600A, TI 4601A, TI 4602A, TI 4700A, TI 4400A, TI 4800A*)
- 7) Pre heat exchanger DI water temperature (*TI 4600B, TI 4601B, TI 4602B, TI 4700B, TI 4400B, TI 4800B*)
- 8) Tower water supply temperature (*TI 4600C, TI 4601C, TI 4602C, TI 4700C, TI 4400C, TI 4800C*)
- 9) Tower water return temperature (*TI 4600D, TI 4601D, TI 4602D, TI 4700D, TI 4400D, TI 4800D*)
- 10) HOA switch for Pump A (*HS 4600A, HS 4601A, HS 4602A, HS 4700A, HS 4400A, HS 4800A*)
- 11) HOA switch for Pump B (*HS 4600B, HS 4601B, HS 4602B, HS 4700B, HS 4400B, HS 4800B*)
- 12) DI water pressure gauge isolation valves (*HV 4600A,B,E,F,G, HV 4601A,B,E,F,G, HV 4602A,B,E,F,G, HV 4700A,B,E,F,G, HV 4400A,B,C,E,F,G, HV 4800A,B,C,E,F,G*)
- 13) DI water pumps isolation valves (*HV 4600W,X,Y,Z, HV 4601W,X,Y,Z, HV 4602W,X,Y,Z, HV 4700W,X,Y,Z, HV 4400W,X,Y,Z, HV 4800W,X,Y,Z*)

- 14) FAULT indicator light on MCC
- 15) READY indicator light on MCC
- 16) RUN indicator light on MCC

Software HMI/EPICS Digital Operator Controls

- 1) Primary Pump Mode
 - a. OFF
 - b. Pump A is primary
 - c. Pump B is primary

Software HMI/EPICS Digital Displays

- 1) Primary Pump Mode switch status
 - a. OFF
 - b. Pump A is primary
 - c. Pump B is primary
- 2) Pump that is running and the pump that is de-energized. (*PDIS 4600A, PDIS 4600B, PDIS 4601A, PDIS 4601B, PDIS 4602A, PDIS 4602B, PDIS 4700A, PDIS 4700B, PDIS 4400A, PDIS 4400B, PDIS 4800A, PDIS 4800B*)
- 3) Failed Primary Pump: Differential pressure across primary pump is low. Logic de-energizes primary pump and energizes backup pump.

Software HMI/EPICS Analog Operator Controls

- 1) DI water temperature

Software HMI/EPICS Analog Displays

- 1) DI water supply temperature (*TT 4600A, TT 4601A, TT4602A, TT4700A, TT4400A, TT4800A*)
- 2) Tower water return line controller output (*IP 4600A/TCV 4600A, IP 4601A/TCV 4601A, IP 4602A/TCV 4602A, IP 4700A/TCV 4700A, IP 4400A/TCV 4400A, IP 4800A/TCV 4800A*)
- 3) Resistivity of circulating loop (*AIT 4600A, AIT 4601A, AIT 4602A, AIT 4700A, AIT 4400A, AIT 4800A*)
- 4) Resistivity of polishing loop (*AIT 4600B, AIT 4601B, AIT 4602B, AIT 4700B, AIT 4400B, AIT 4800B*)

Software HMI/EPICS Alarms (via EPICS Alarm Handler)

- 1) Supply temperature high and low
- 2) Tower water differential pressure high and low
- 3) Circulating loop resistivity low
- 4) Polishing loop resistivity low
- 5) Primary pump failed, backup pump running (differential pressure is normal)
- 6) No flow (low differential pressure on both pumps)

Control Logic Description

In the OFF mode, the primary and backup pump will be de-energized .

In the PUMP A IS PRIMARY mode, the Pump A will be energized and the Pump B will be de-energized. After a delay period, the Pump A will be periodically checked for low flow. If low flow is detected, Pump A will be de-energized and Pump B will be energized. An alarm will be generated to the operator. After a delay period, the Pump B will be periodically checked for low flow. If low flow is detected, Pump B will be de-energized and a “No Flow” alarm will be generated to the operator.

In the PUMP B IS PRIMARY mode, the Pump B will be energized and the Pump A will be de-energized. After a delay period, the Pump B will be periodically checked for low flow. If low flow is detected, Pump B will be de-energized and Pump A will be energized. An alarm will be generated to the operator. After a delay period, the Pump A will be periodically checked for low flow. If low flow is detected, Pump A will be de-energized and a “No Flow” alarm will be generated to the operator.

For both the PUMP A IS PRIMARY and PUMP B IS PRIMARY modes, the Tower Water Return Line Control Valve is modulated by a PID algorithm to maintain the DI Water Temperature Setpoint.





