

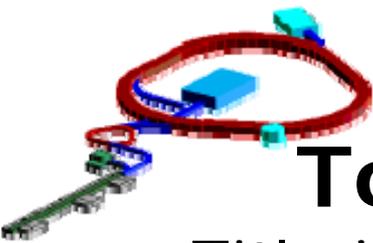
The Beam Collimator System of J-PARC Rapid Cycling Synchrotron

HB2008

presented by

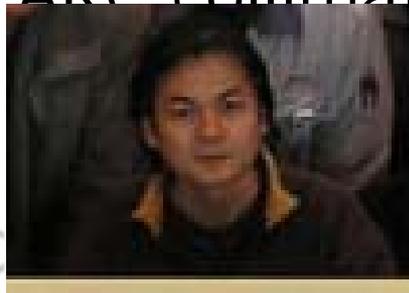
Kazami Yamamoto

J-PARC Accelerator Physics Group



Topics in this presentation

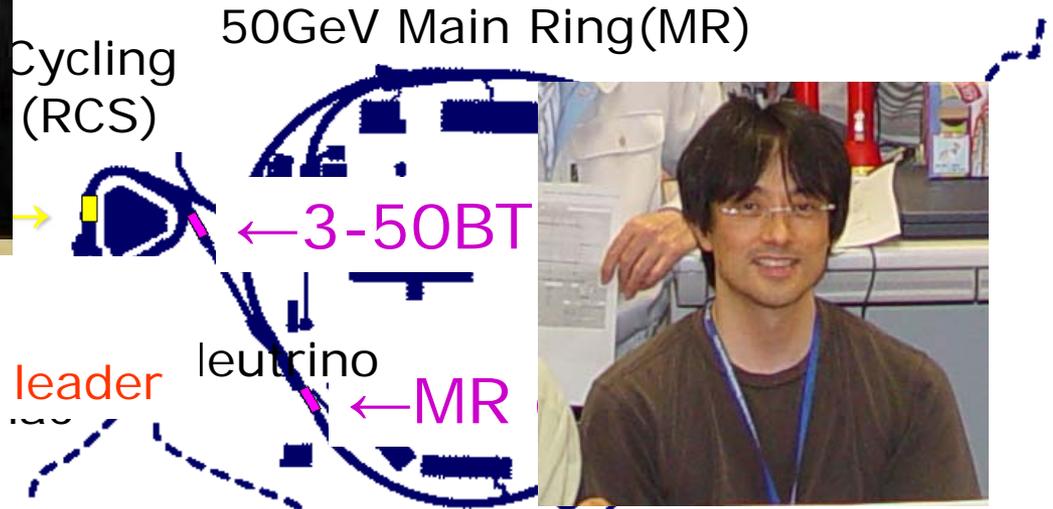
- Title in the program is "J-PARC collimation system experience"



RCS

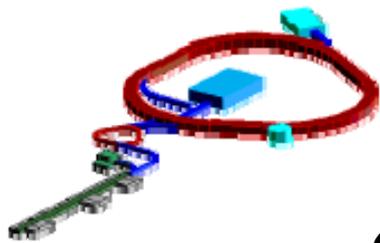
Dr. Ikegami

Linac commissioning leader



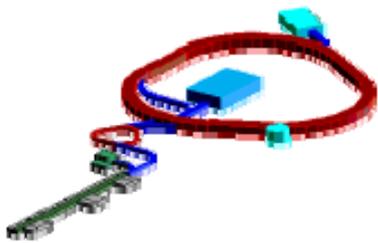
- L3BT scraper...Did not use since linac beam Dr. Koseki
- 3-50BT and MR collimator...Did not have MR commissioning leader
commissioning have just started

Topic is RCS collimator



Outline of presentation

- Motivation
- Research and Development of RCS collimation system
- Results of first beam commissioning
- Summary



Motivation



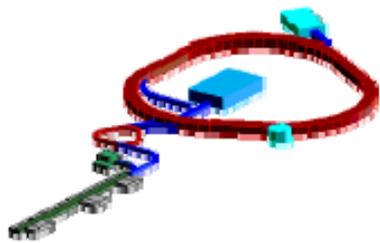
The RCS ring is designed to deliver the 3GeV, 1MW pulsed proton beam to the spallation neutron target and the MR, hence our motivation is to achieve such high intense beam.

In order to achieve such high intense beam, the most important issue is to reduce and control(localize) the beam loss.

We have designed the beam collimator system for the purpose of the beam loss localization.

The design issues of the beam collimator system are:

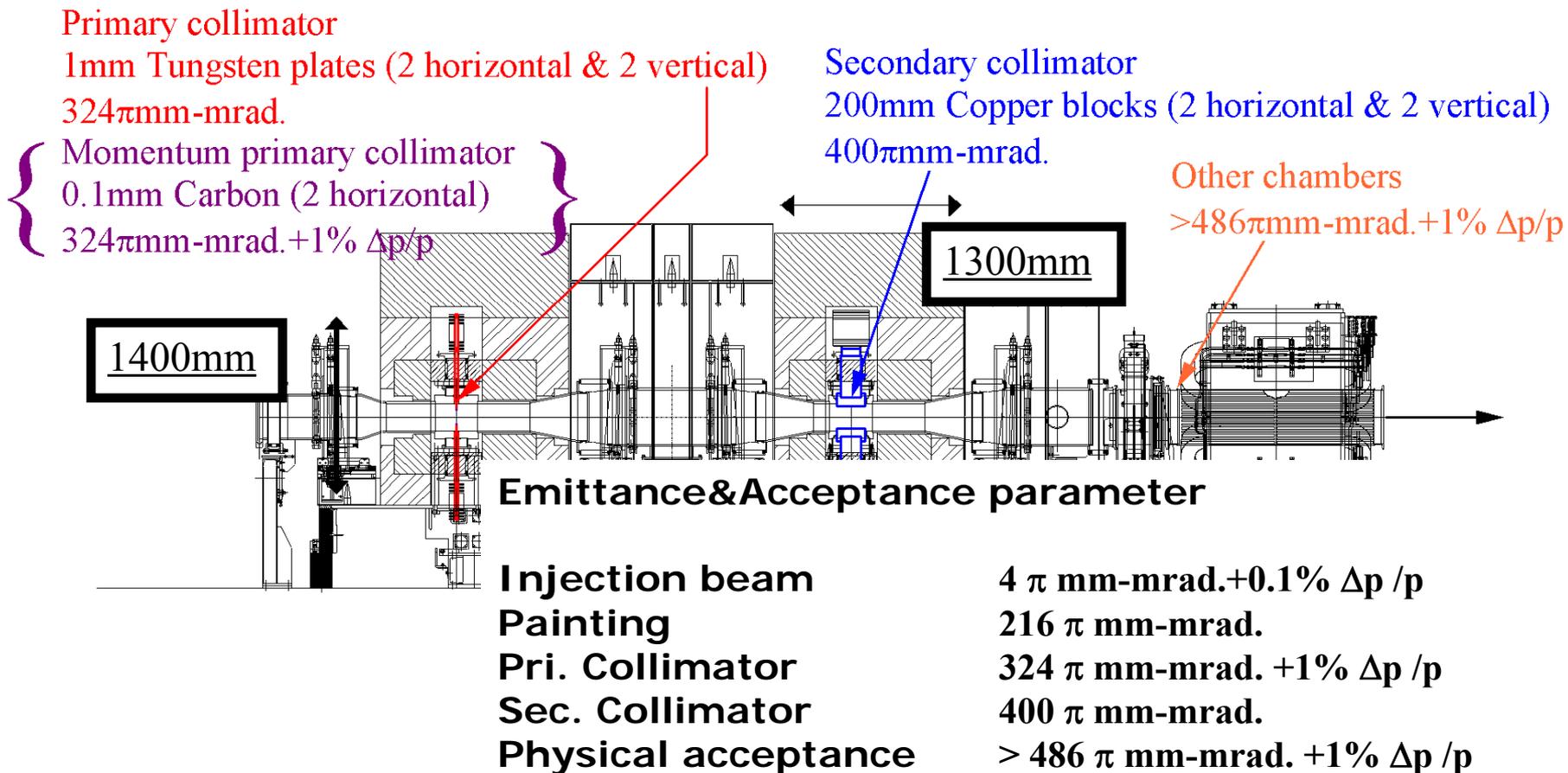
- 1) High localization efficiency of the beam loss. ($< 1\text{W/m}$)
- 2) Enough shielding thickness to reduce the residual dose.
- 3) Easy maintenance system to save a labor close to the collimator.
- 4) Choice/development of the rad-hard components.

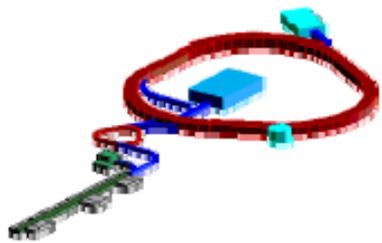


Construction of the RCS collimator

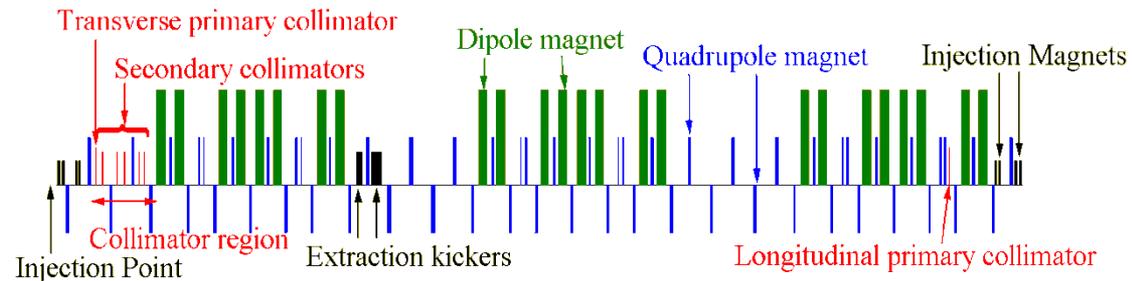
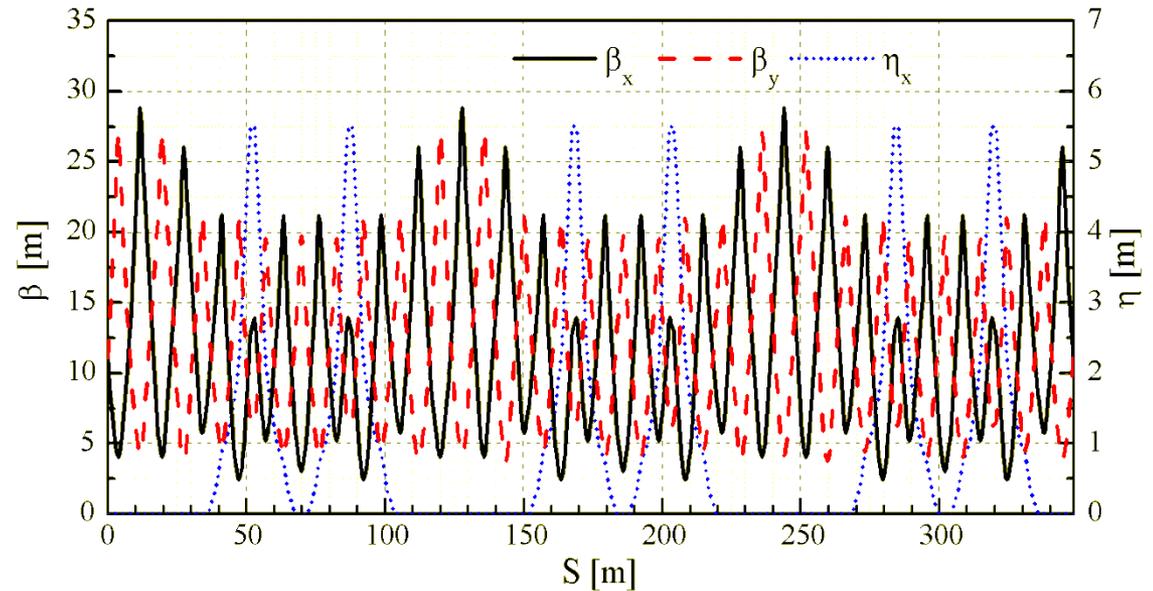
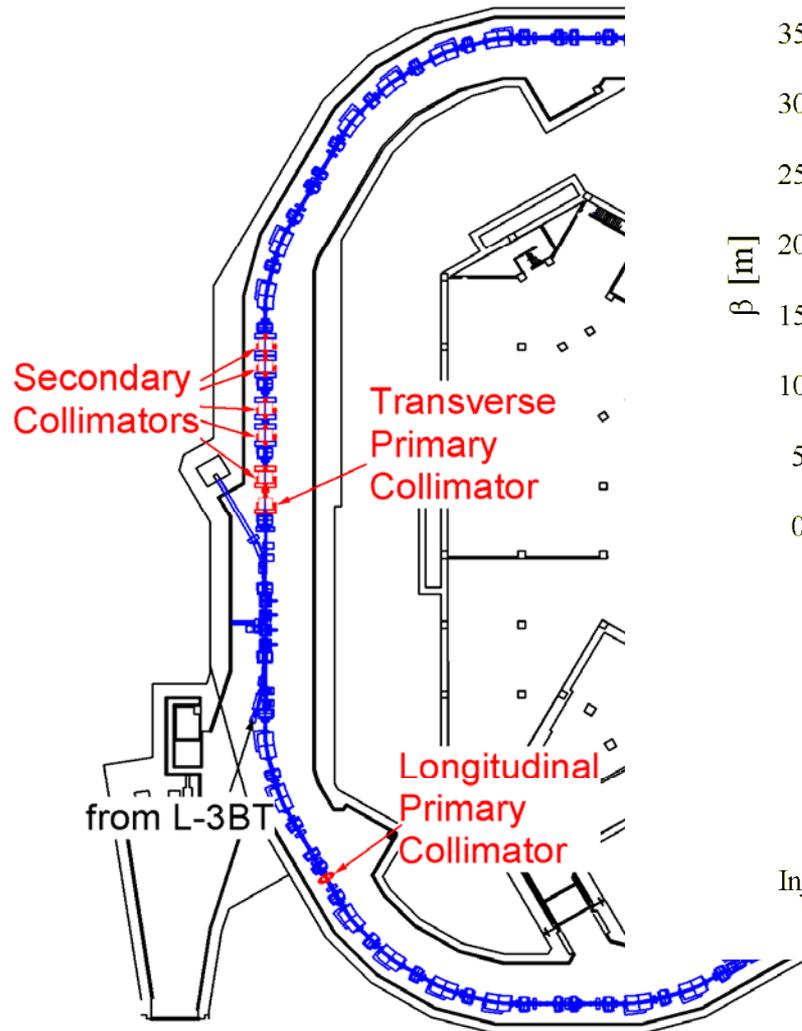


We use the two stage collimation system for the RCS collimator

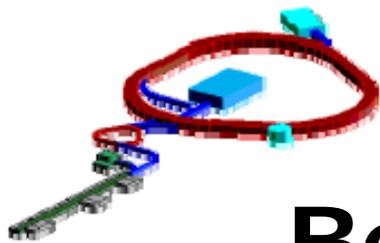




RCS Parameters



3GeV RCS Twiss Parameter



Beam loss distribution

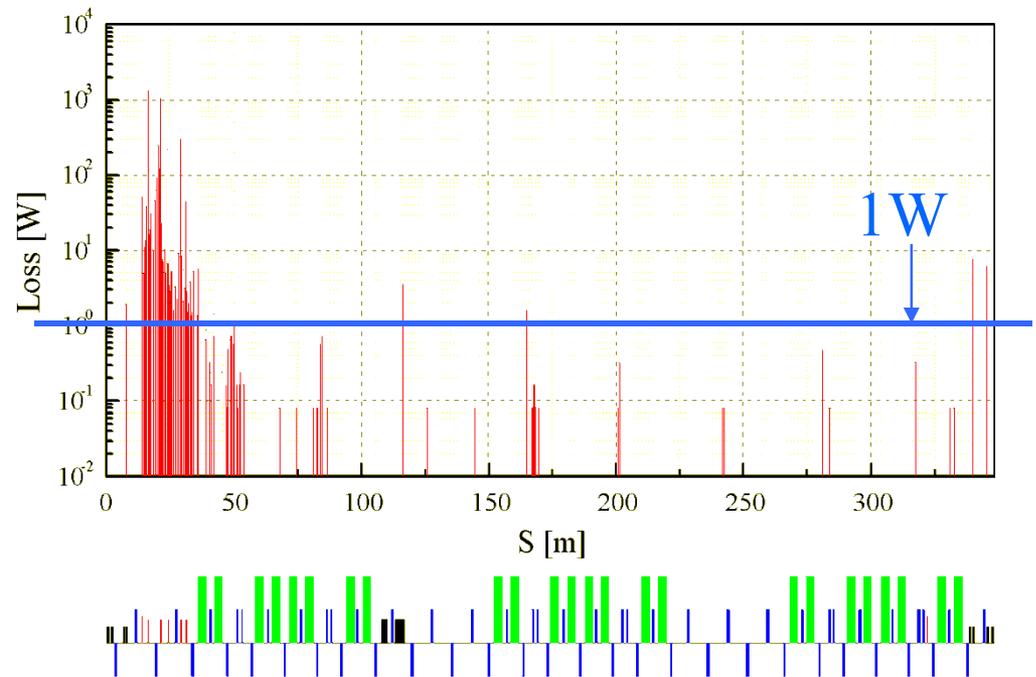
- Calculated by STRUCT code (FNAL)

Linear transfer matrix
multiple scattering

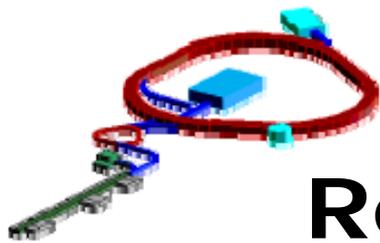
- Beam Halo Transverse: $324 < \epsilon_{x,y}$
< 344π mm-mrad. 4 kW were assumed

- Maximum loss point is first secondary collimator (1.2 kW).

- 98 % lost particles were localized in the collimator region.
→ 1 W/m criteria was almost cleared!



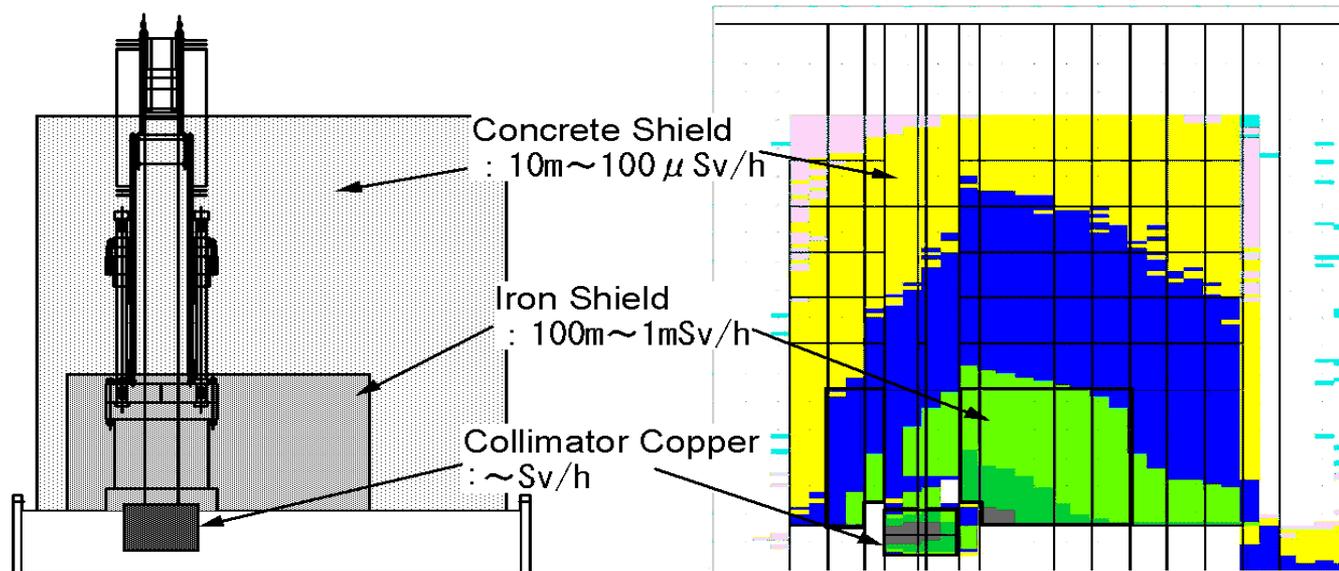
Results of Transverse Halo Collimation



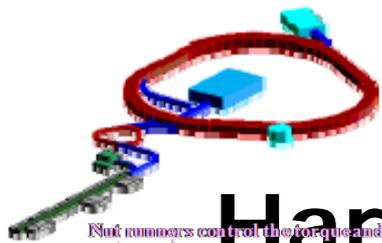
Residual dose estimation

We designed the shielding wall for the sake of residual dose suppression less than 1W/m level (<1mSv/hr.)

- Calculated by MARS code (FNAL)
- Covered with 300mm inner iron and 500mm outer concrete
- Assumed that 400MeV, 1.2kW loss is localized on the secondary collimator
- Residual dose rate after 1 month irradiation/1 day cooling

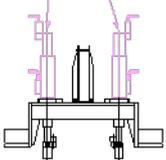


Outside of shield: ~hundreds of μ Sv/h = 1 W/m order



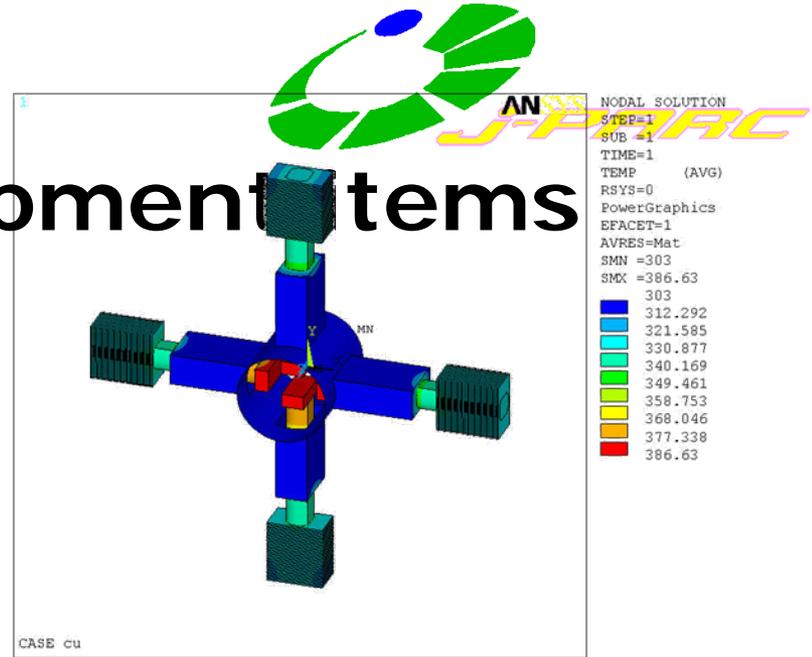
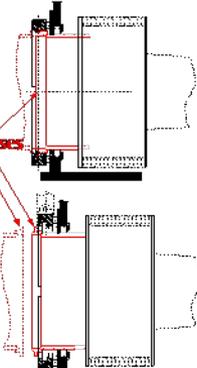
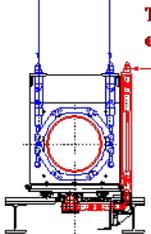
Hardware development items

Not numbers control the torque and the turn numbers



These screws open/close the quick-coupling clamp.

This screw separates/closes each flange.



Collimator Block

Shielding design

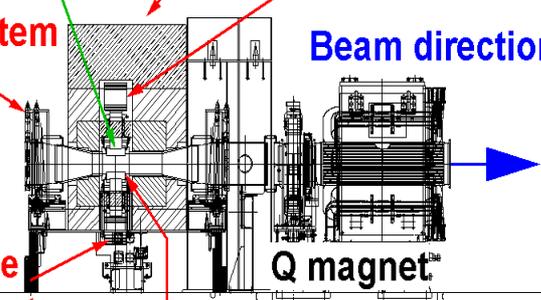
Development of the remote clamp system

Cooling system

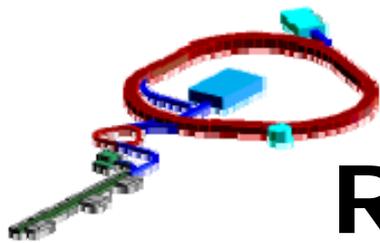
Beam direction

Development of the motor, cable, connector

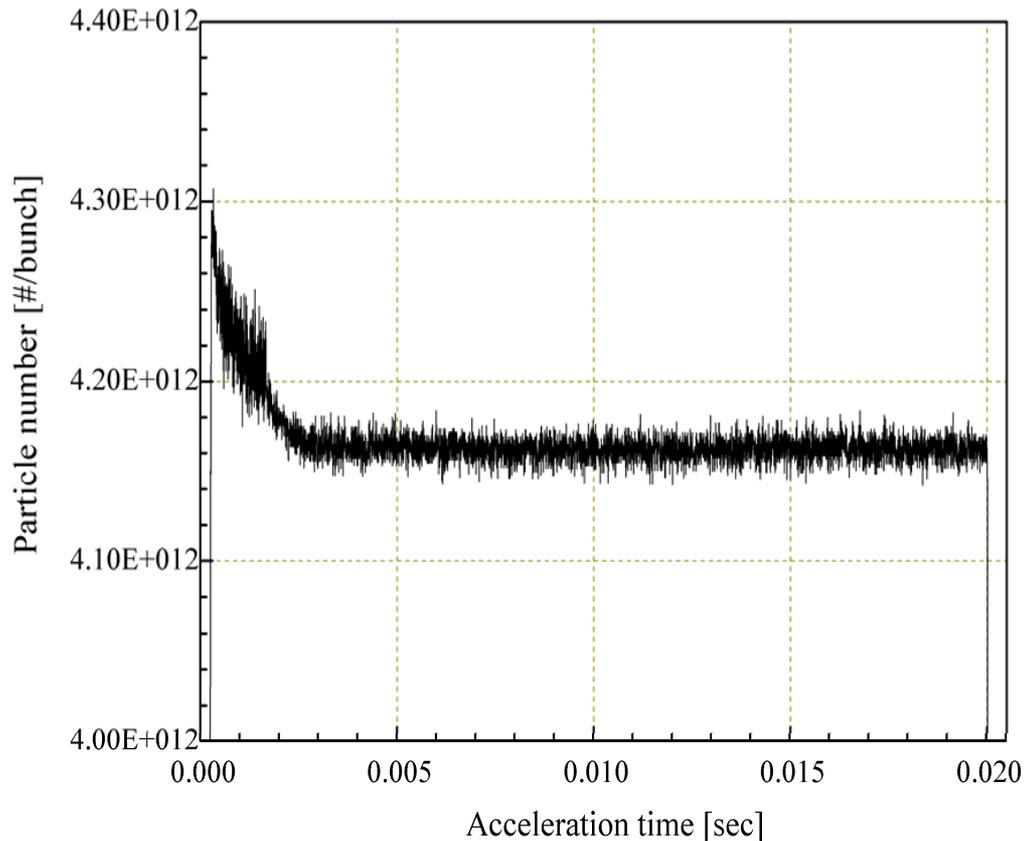
Vacuum conditioning and measures for the secondary electron emission



Au

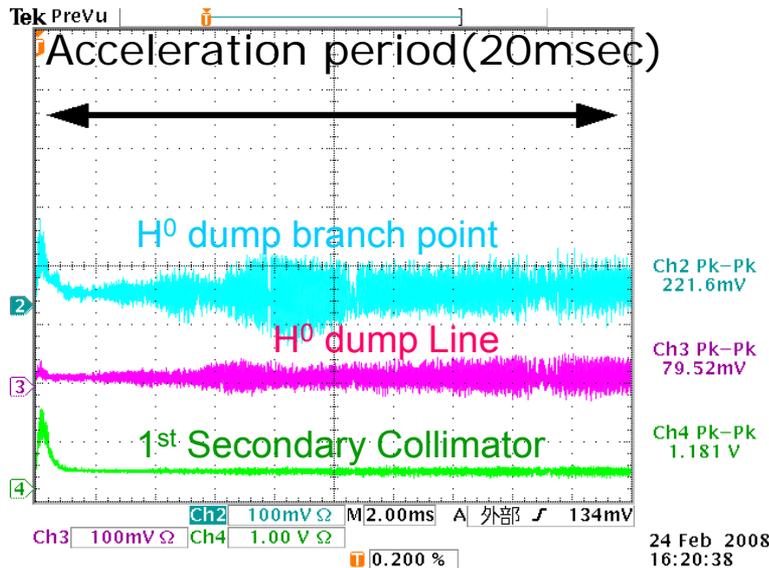
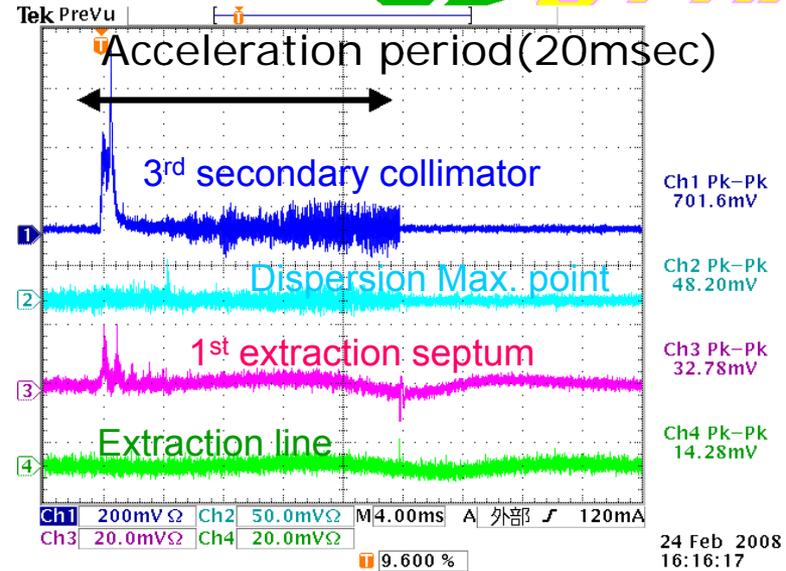
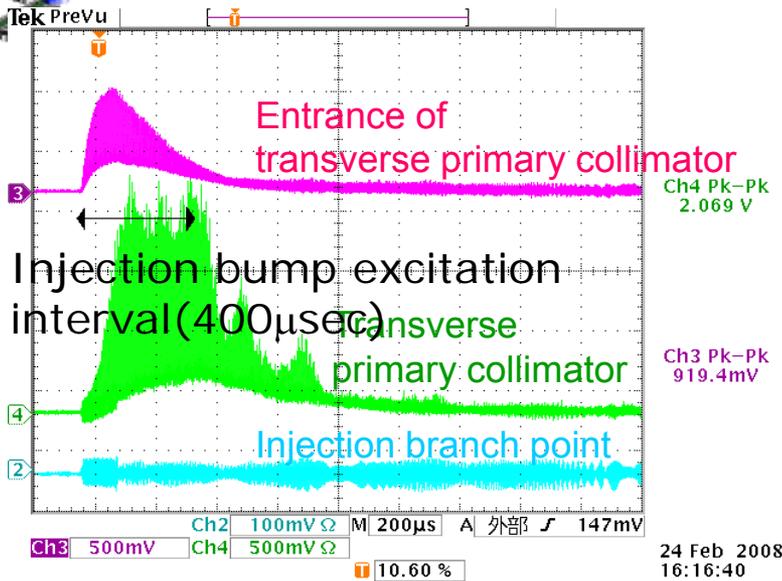
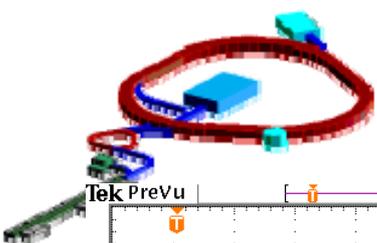


Results of first beam commissioning



- The total beam power was restricted by the capacity of extraction dump (Capacity is an average of 4kW an hour).
- We usually use a few kW beam for continuous beam commissioning, but only few minutes we can accelerate high intensity beam (more than 100kW)
- In this case, the number of particles per bunch correspond to more than 50kW (4.3×10^{12}) was accelerated. The painting bump did not excited and all injection beam have entered into the ring center orbit in piles.
- The loss during the acceleration period was 3.4%.

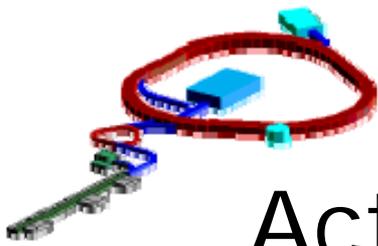
Beam loss point



BLM signals appeared at

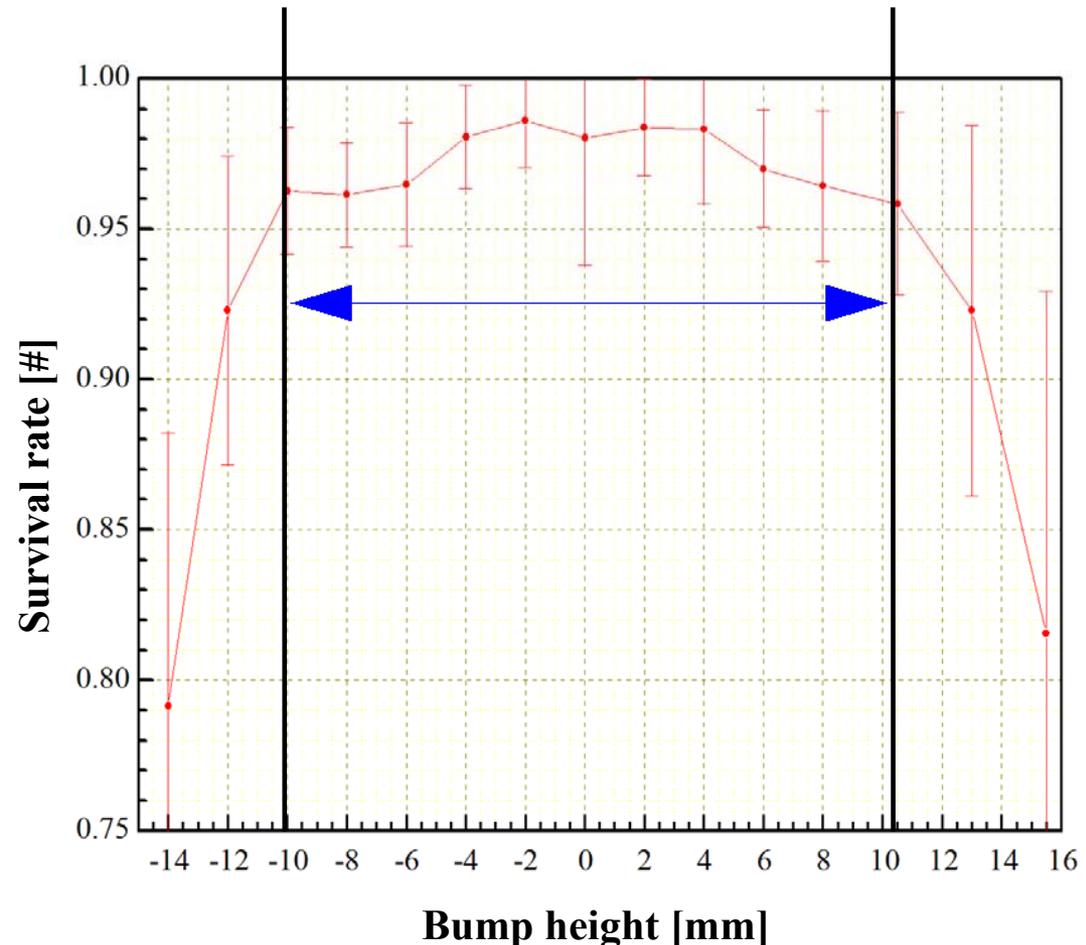
- Entrance of transverse primary collimator chamber
- H⁰ dump branch point
- Transverse collimators
- 1st extraction septum

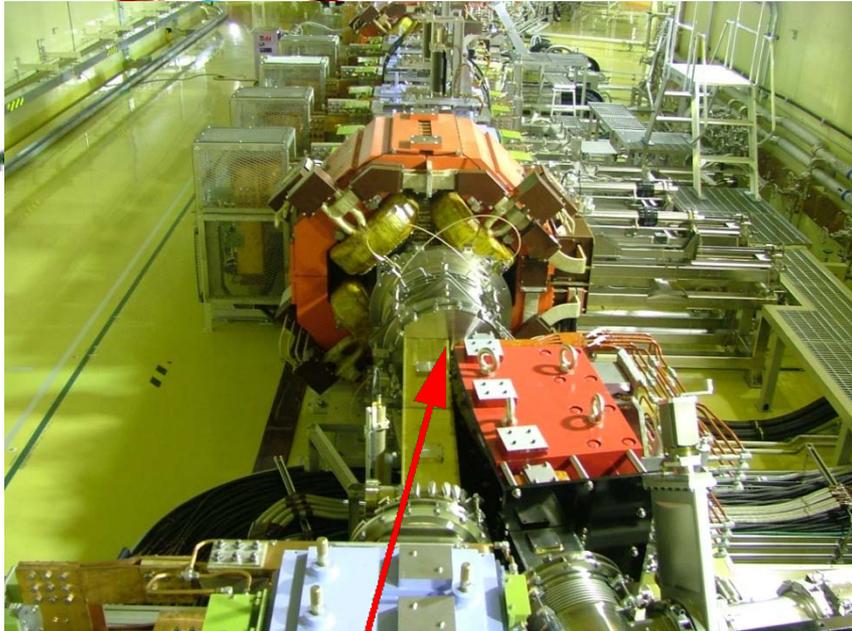
It is remarkable that the BLM of each collimator is put on the outside of shielding, those are further than the other BLMs, nevertheless signals were much larger !!



Actual collimator acceptance

- We investigated the actual transverse primary collimator acceptance.
- In this study, we shifted the injection bump height and the linac beam came into the outside of beam center. (Offset injection)
- Then, we measured the survival rate by the wall current monitor.
- The beam current suddenly decreased at 10mm bump height and it corresponded to about $324\pi\text{mm-mrad}$.
- The position of the transverse primary collimator was approximately right.





BM chamber : 5 μ Sv/hr.

Highest point: 380 μ Sv/h

Crotch of

H0 dump CT chamber
: 10 μ Sv/hr.

H0 dump branch →

**Caused by a mistake
of septum setting**

Collimator chamber : 140 μ Sv/hr.

H0 dump branch : 380 μ Sv/hr.

1st Foil : 30 μ Sv/hr.

Second highest point: 140 μ Sv/h

Entrance of primary collimator chamber

Caused by the foil scattering of cir

Dispersion Max point

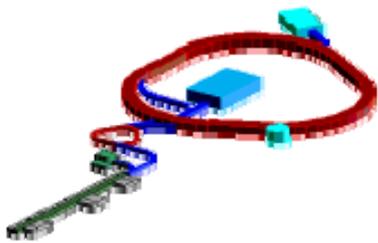
90-deg. dump : 10 μ Sv/hr.

Practically, each collimator would have much larger residual dose. but we could not measure the inside of collimator shielding. We could detect only the residual dose on the outside of shielding and It is a background level.

Beam collimator system has good performance!!

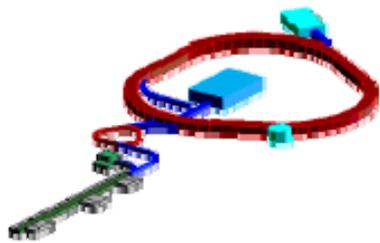
Aug. 2008

Kazumi Yamamoto

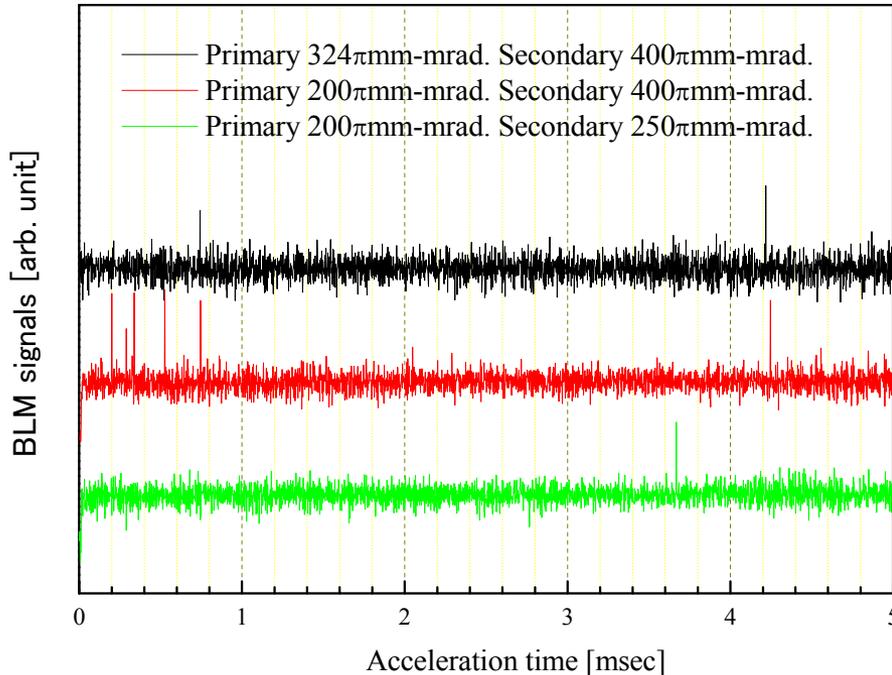


Does the system perform as expected? Did the simulations/calculations performed during the design stage accurately predict the actual performance?

→For the moment, We think our collimation system has enough performance according to above reason.



Acceptance ratio of primary and secondary



BLM signals of dispersion maximum point after collimator region

Black

:Designed acceptance

Pri. 324π : Sec. $400\pi \doteq 4:5$

Red

:"Unbalanced" acceptance ratio

Pri. 200π : Sec. $400\pi = 1:2$

Green

:Design acceptance ratio

Pri. 200π : Sec. $250\pi = 4:5$

→Unbalanced acceptance ratio caused leakage loss from collimator region

Designed acceptance has enough performance

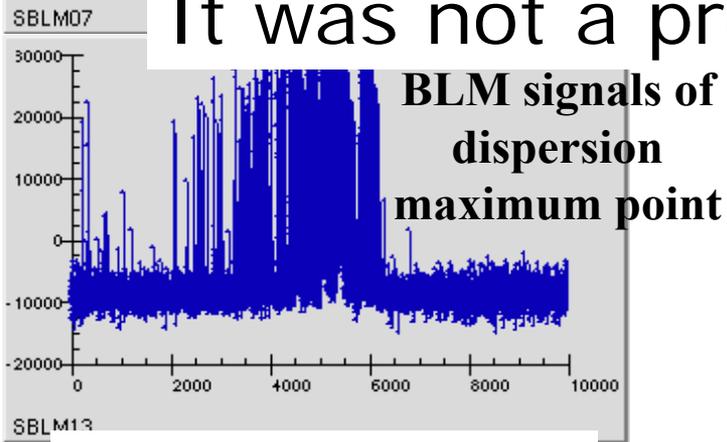
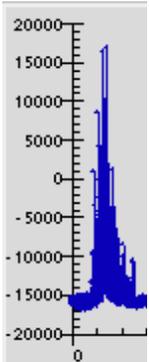


Longitudinal collimation

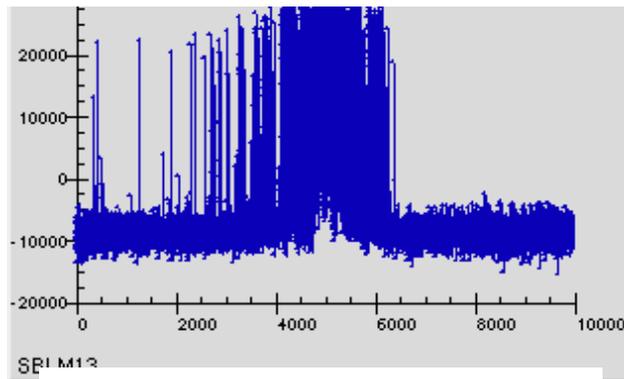
- However, the collimation system did not work as our expectation in some respects.

● Fortunately, at present there was no longitudinal halo in usual operation because of good performance of the ring RF system and the Linac chopper.

It was not a problem for the moment.

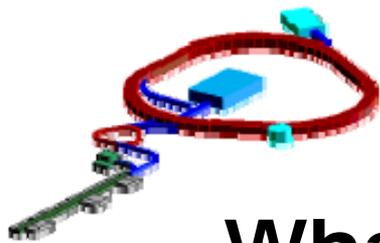


Not insert the longitudinal collimator



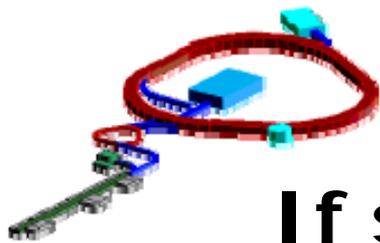
Insert the longitudinal collimator

were lead on the transverse secondary collimators, but BLM signal of the dispersion maximum point was scarcely reduced. 16



What are the major limitations in performance? Were they known in the design stage?

- We did not reach the technical limitation because now limitation is caused by the dump capacity.
- High power (more than 100kW) test will be carried out next December and major limitation will become clear.



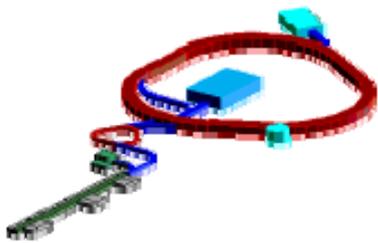
If someone were to begin now designing the same type of system for a similar machine, what is the one piece of advice that you would give them?

- The most important issue is measures for high radiation.

(Easy maintenance system and choice/development of high durability component)

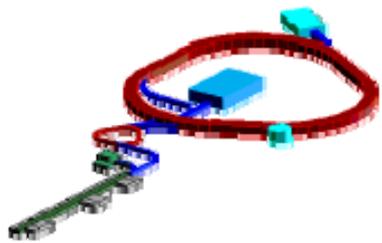
- you should make effort to reduce the source of longitudinal halo.

(Longitudinal collimation is difficult. Reinforce not the longitudinal collimator but the ring RF system or linac chopper system)

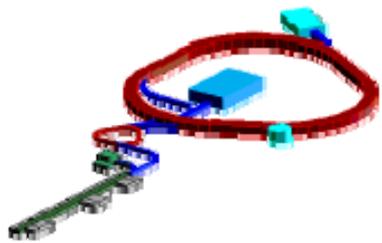


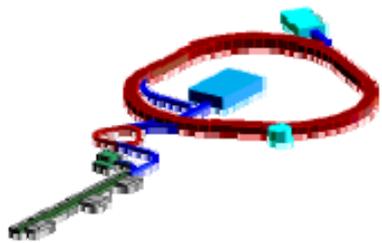
Summary

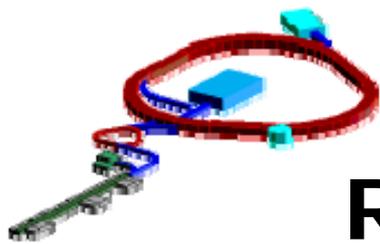
- We optimized the collimation system for J-PARC RCS and developed the collimator components as the requirements.
- Our collimation system had enough performance during the first commissioning period.



**Thank you for your
attention**





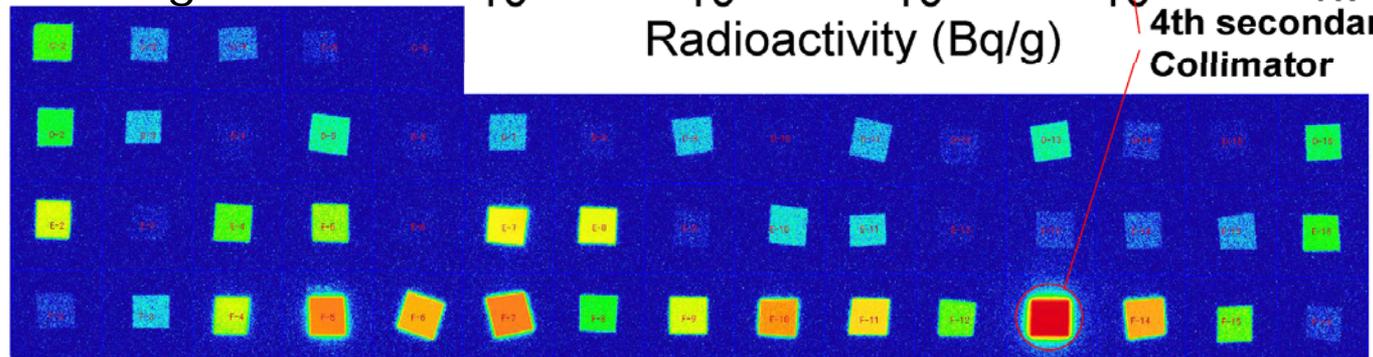
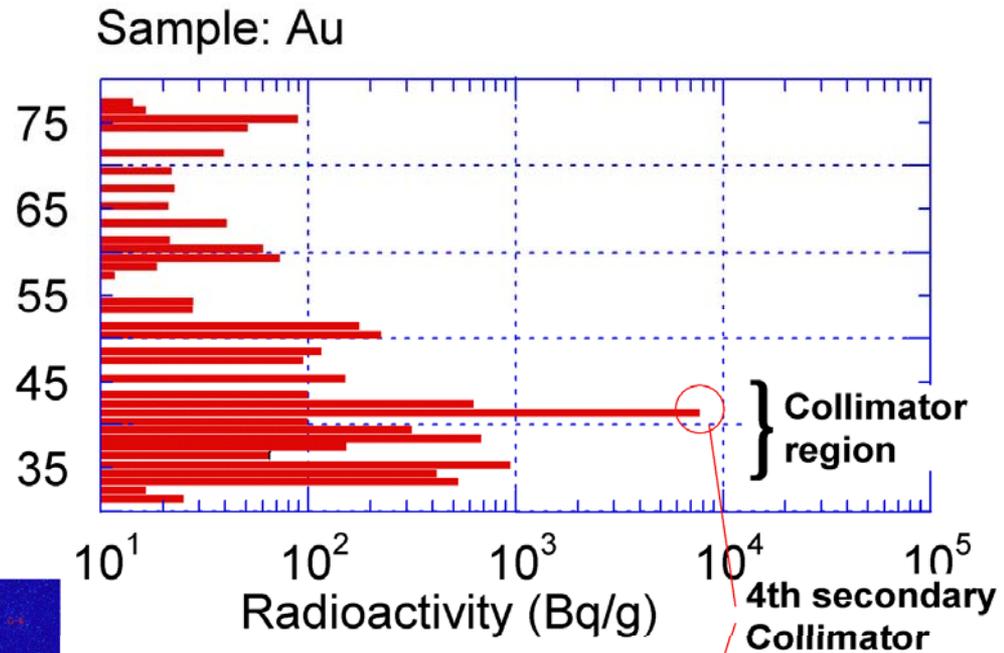


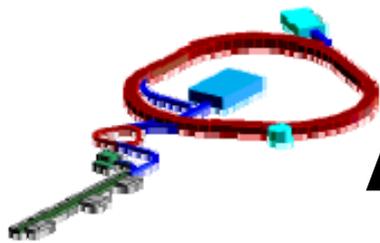
Radio-activation sample

We put many gold samples on the vacuum chamber, in the shielding walls of collimators, or on the tunnel wall.

The most radio-activated point is 4th secondary collimator.

On the other hand, the calculation indicated 1st secondary collimator is highest loss point.





Acceptance optimize



● Collimation efficiency

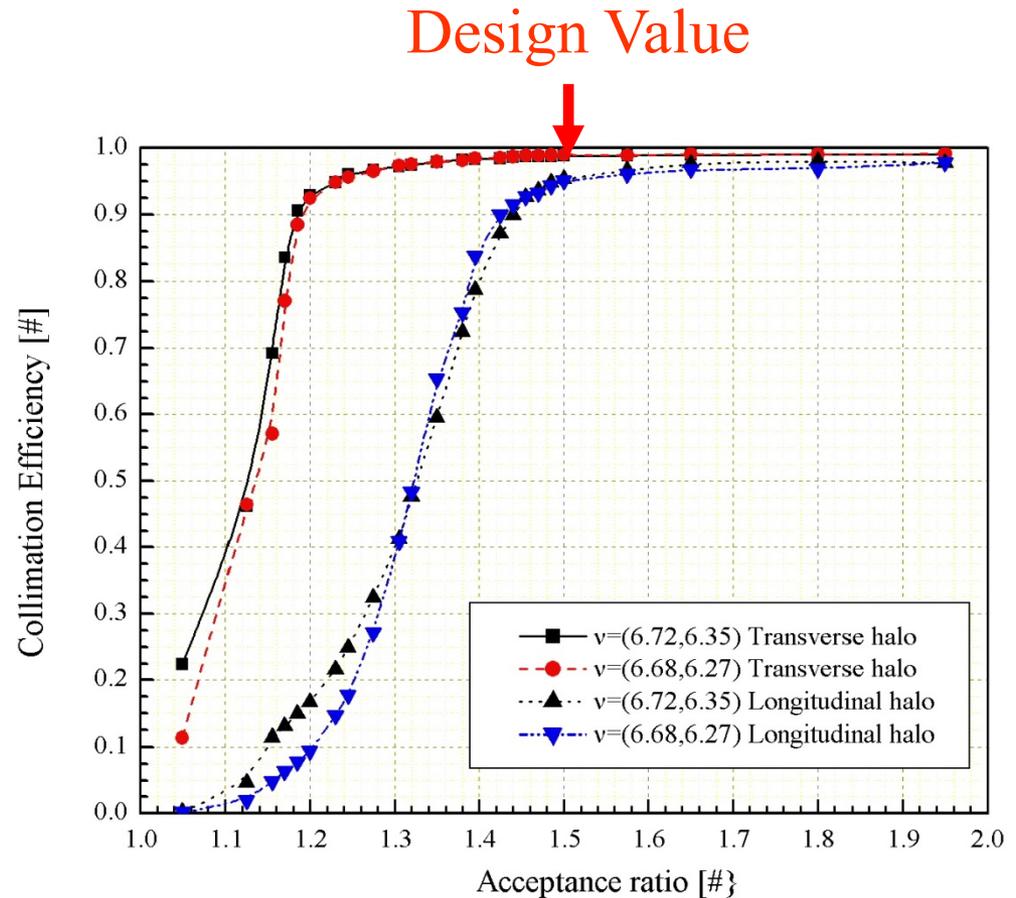
Lost particles in the collimator region

All lost particles

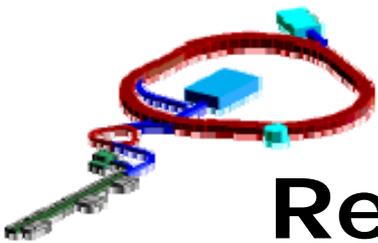
● Acceptance ratio

Physical acceptance [$\pi\text{mm-mrad.}$]

Collimator acceptance [$\pi\text{mm-mrad.}$]



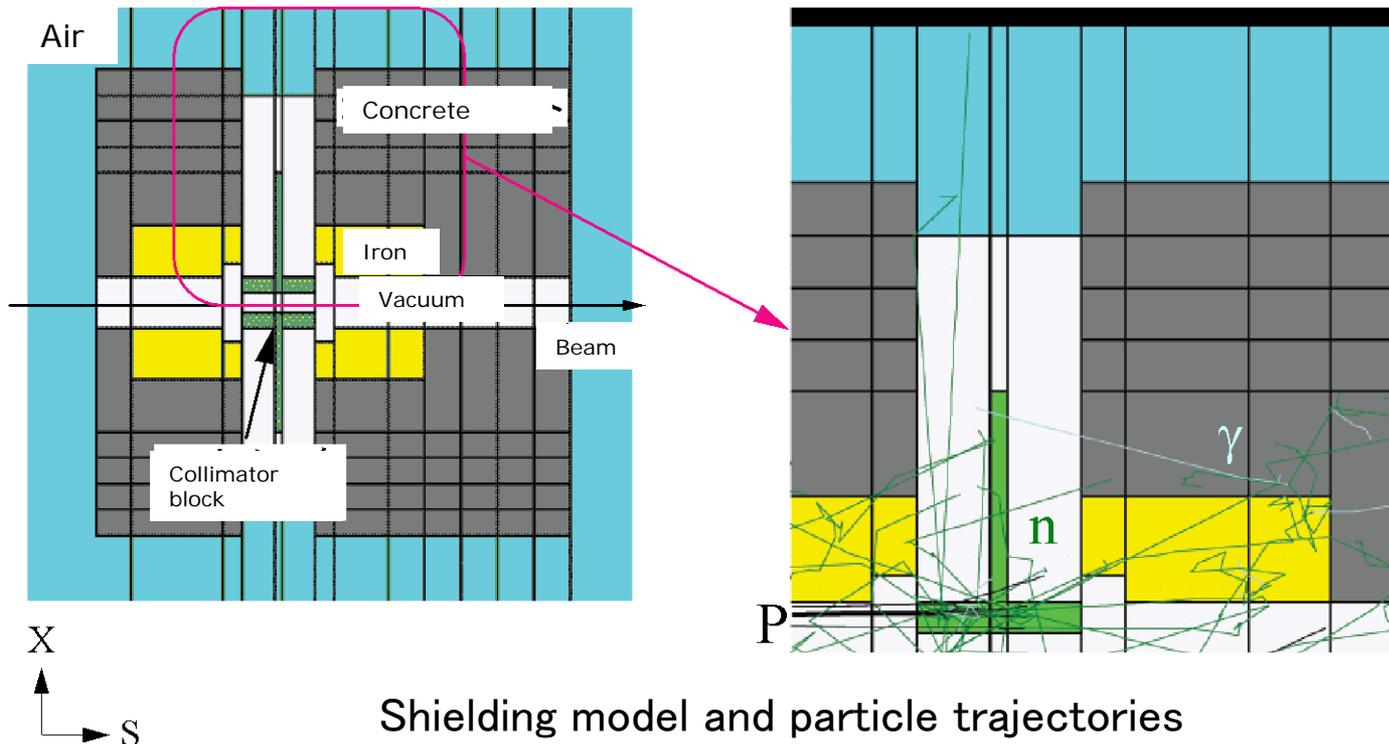
**Collimation efficiency dependence
on the collimator acceptance**



Residual dose estimation

Shielding design for the sake of residual dose suppression under 1W/m level (<1mSv/hr.)

- Calculated by MARS code (FNAL)
- Covered with 300mm inner iron and 500mm outer concrete
- Assumed that 400MeV, 1.2kW loss is localized on the secondary collimator



Shielding model and particle trajectories

Development of Rad-Hard Components



Gamma-ray irradiation experiment of the collimator components (motors, cables, connectors) were performed by a Co-60 gamma-ray irradiation facility.



Established high rad-hard components, especially the stepper motor had high durability over 100MGy gamma-ray irradiation.



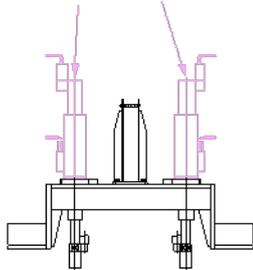


Remote clamp system



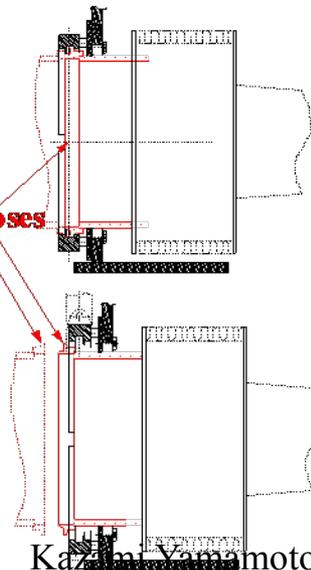
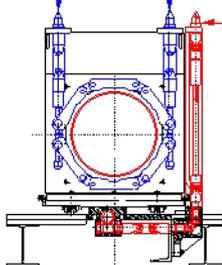
- We developed the remote clamp handling system to reduce the radiation exposure during the maintenance procedure.
- We can maintain several meter away from the collimator chamber by using the nutrunners and the remote clamp handling system.
- First we connect the nutrunners on the screws which move its frange and clamp.

Nut runners control the torque and the turn numbers.



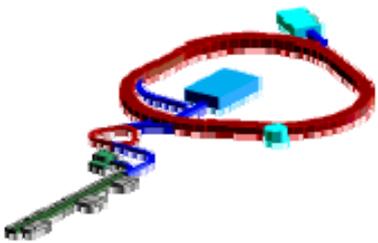
These screws open/close the quick-coupling clamp.

This screw separates/closes each flange.



Aug. 2008

Kazuhiko Yamamoto

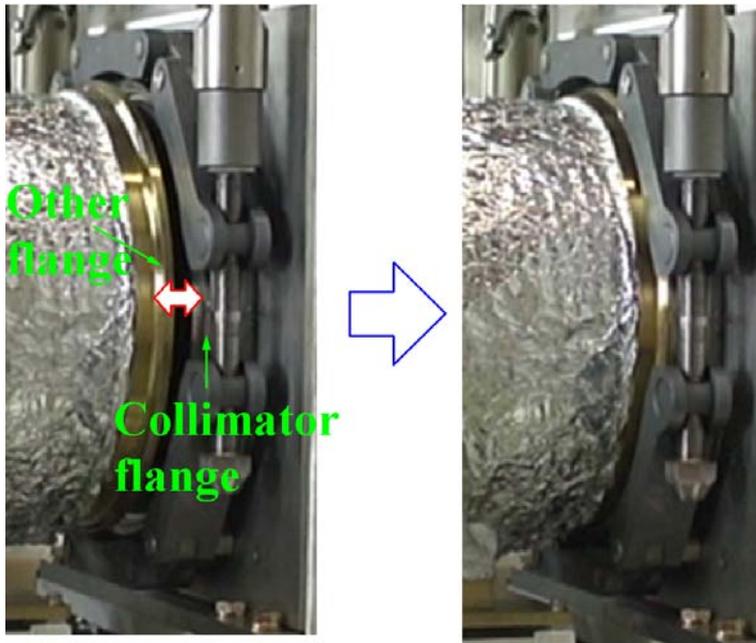


Remote clamp system



- The nutrunners control the separation of each flange and closing torque of quick-coupling clamp.

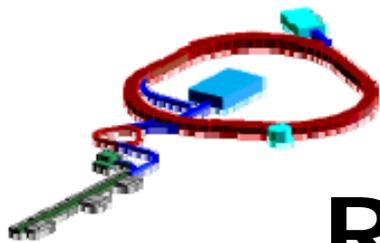
○ Flange movement



○ Clamp closing



- 1mm positioning error of flange can be corrected by the inner guide.
- Finally we connected all remote clamps less than $5 \cdot 10^{-11} \text{Pa} \cdot \text{m}^3/\text{sec}$ He leak rate.

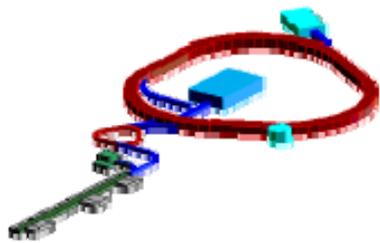


Results of first beam commissioning

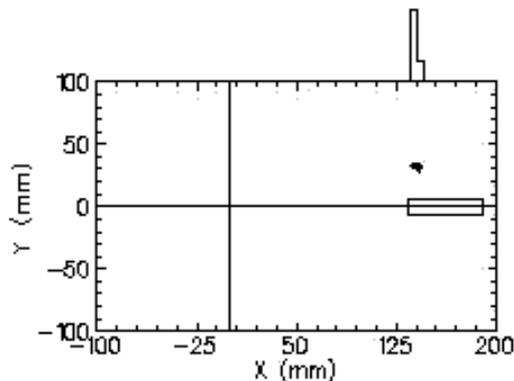
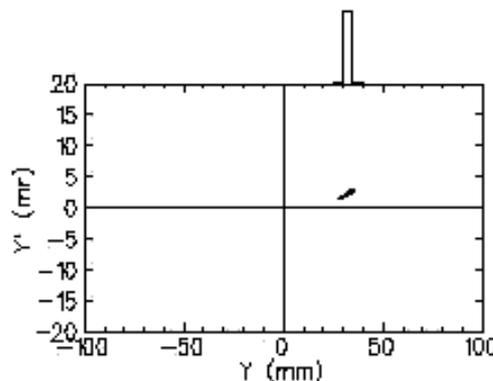
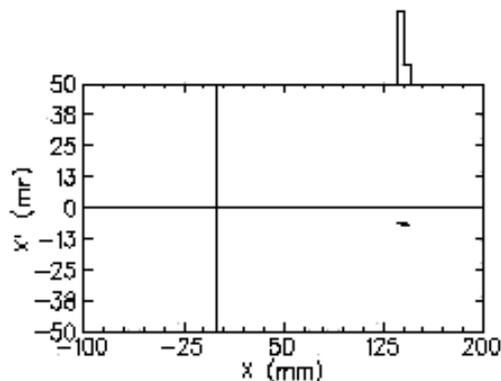
- During the first commissioning, we set the all collimators as designed acceptance.

(Pri. Collimator 324π mm-mrad. $+1\% \Delta p / p$, Sec. Collimator 400π mm-mrad.)

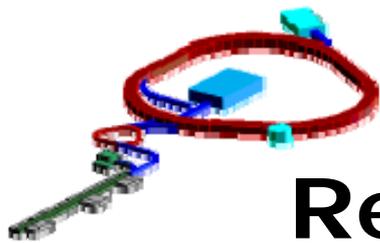
- In this condition, the beam loss monitor signals appeared at next point:



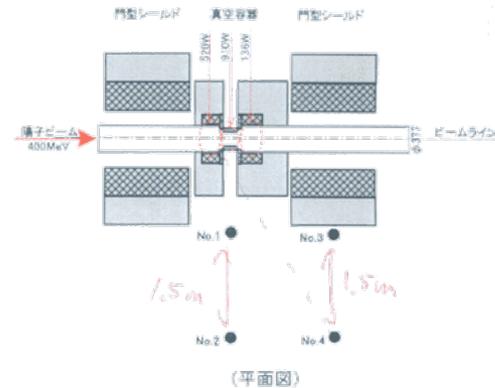
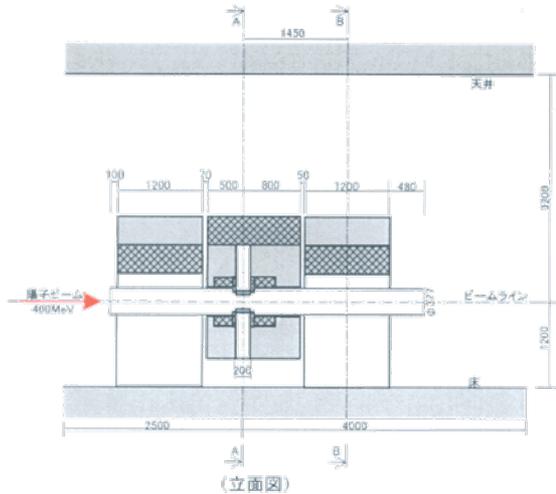
Beam Tracking with Space Charge



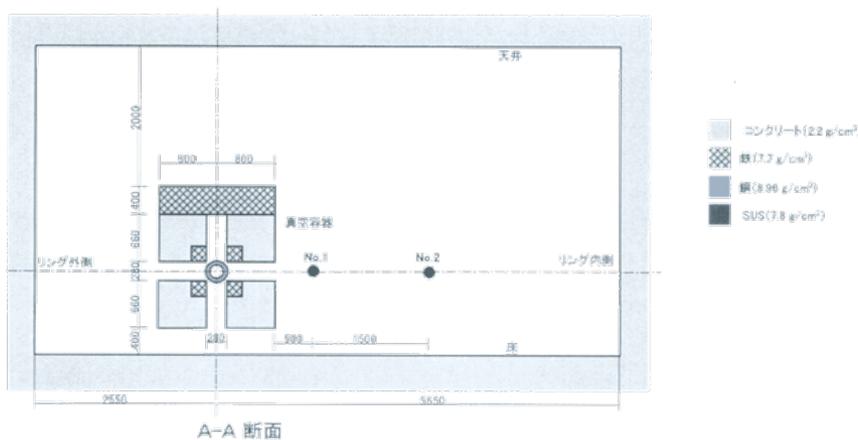
- Calculated by ACCSIM code (TRIUMF)
- Particle number corresponded to 1MW beam power.
- Include painting injection process.

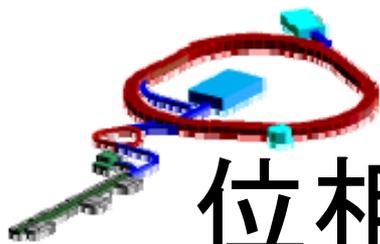


Residual dose estimation

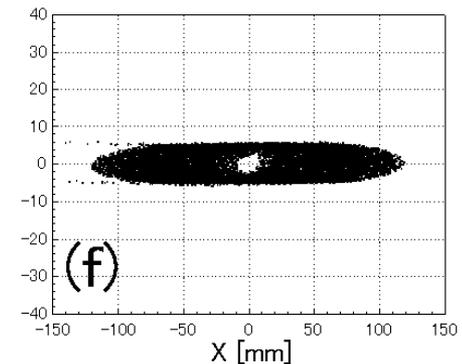
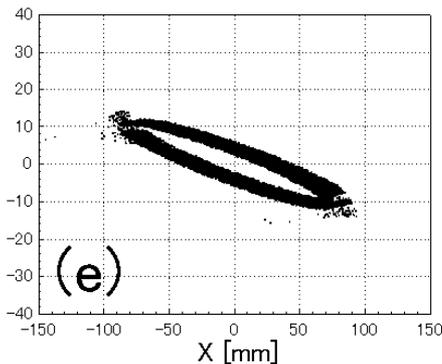
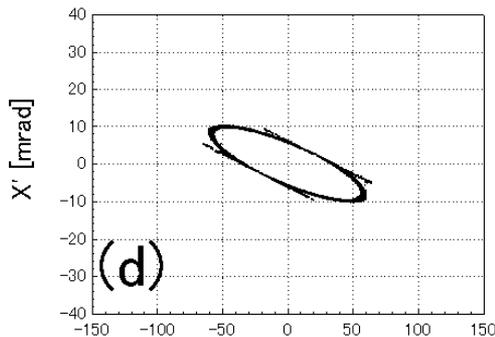
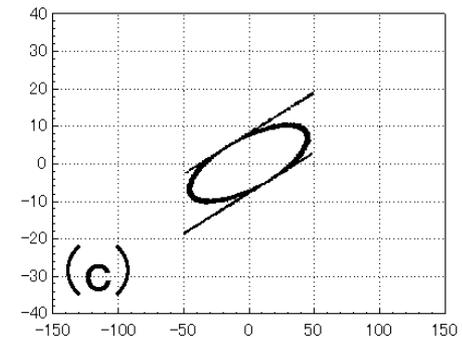
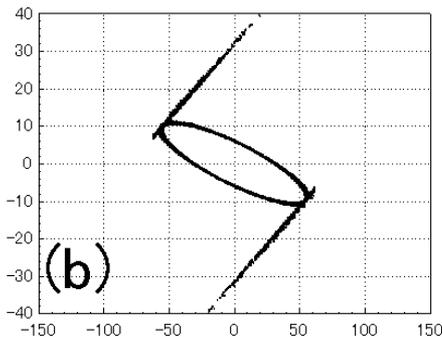
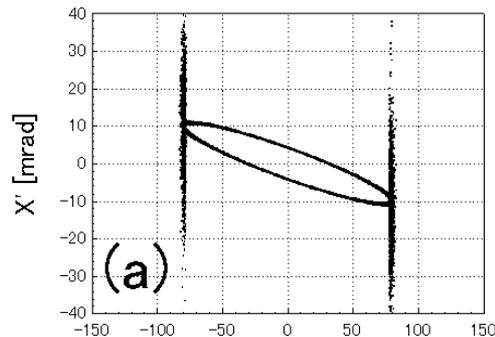


- Calculation result of PHITS, DCHAIN-SP and QAD-CGGP2 codes
- **400MeV, 1.2kW** loss at first secondary collimator
- Calculation include the effect of all activated materials (Collimators, shields, chambers and tunnel walls)
- Residual dose rate after **1 year irradiation/1 week cooling**
 - at point No.1 : 15.9mSv/hr.
 - at point No.2 : 2.78mSv/hr.
 - at point No.3 : 36.5mSv/hr.
 - at point No.4 : 189mSv/hr.



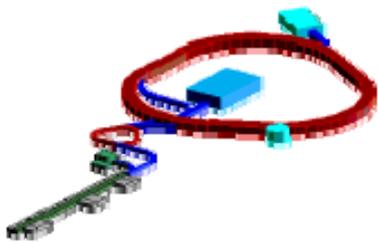


位相空間内での粒子の運動



(a) プライマリーコリメータ直後 (b)(c)(d) 一台目、三台目、五台目のセカンダリーコリメータ直後
(e) コリメータ直後の偏向電磁石二台通過後 (f) コリメータ後最初のディスパージョン最大位置

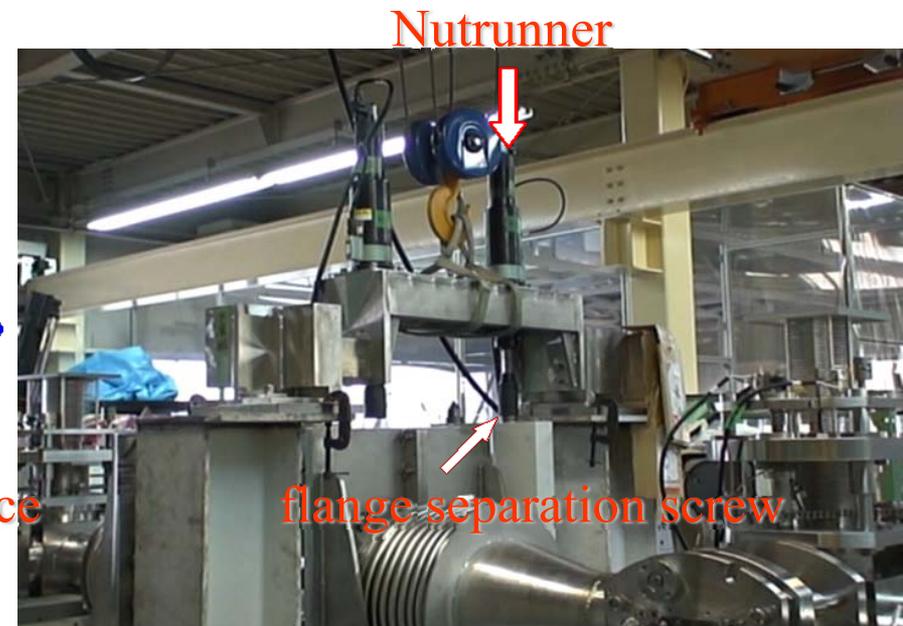
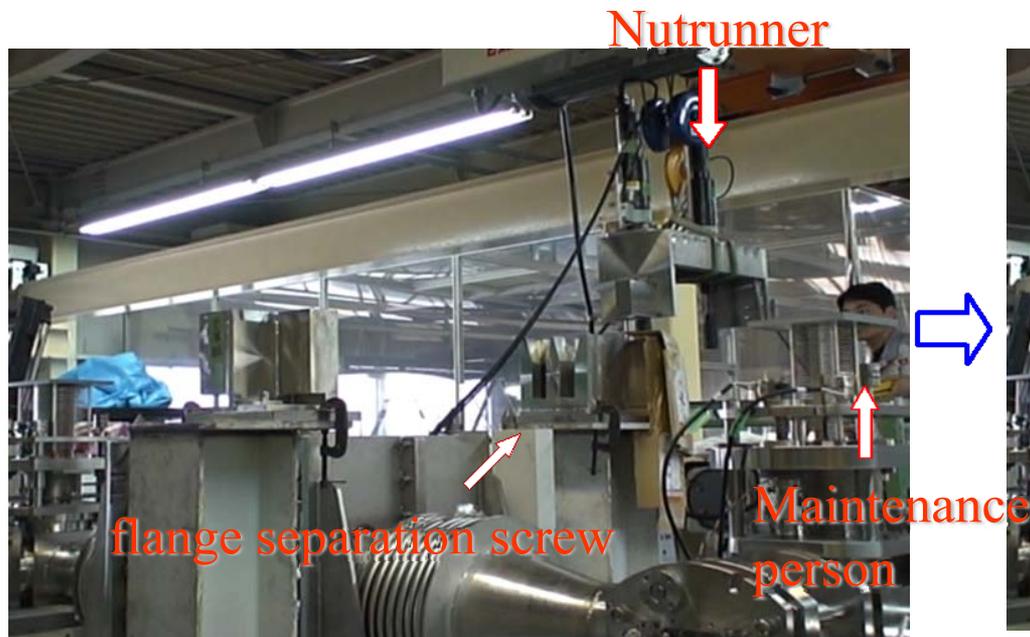
ディスパージョンのある領域で、プライマリーコリメータで受けた散乱角が小さいがモメンタムは大きく失った粒子がロス→コリメーション効率が100%にならない

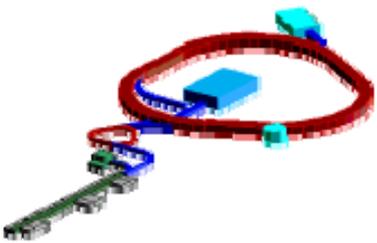


Remote clamp system



First step : We set the nutrunner on the flange separation screw from several meter away from the collimator chamber.



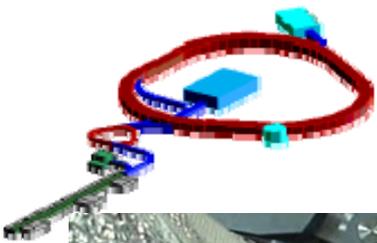


Remote clamp system

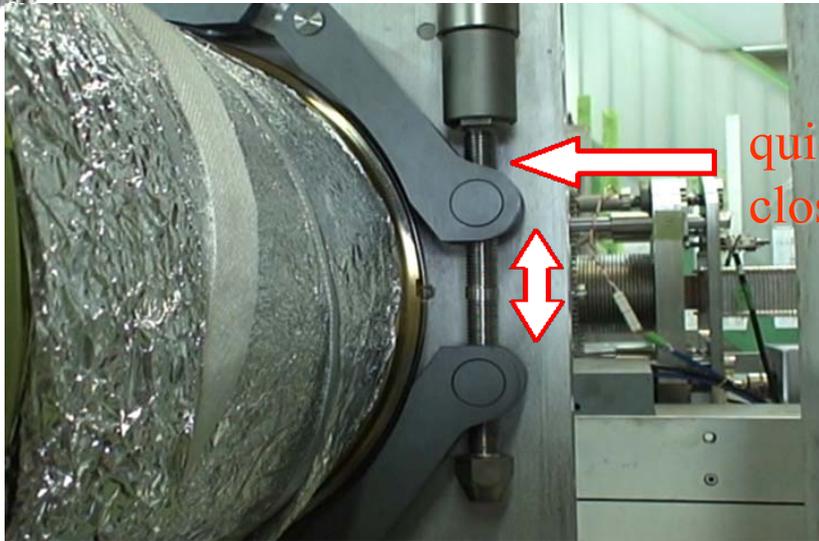


Second step : The nutrunner close the separation of each flange.

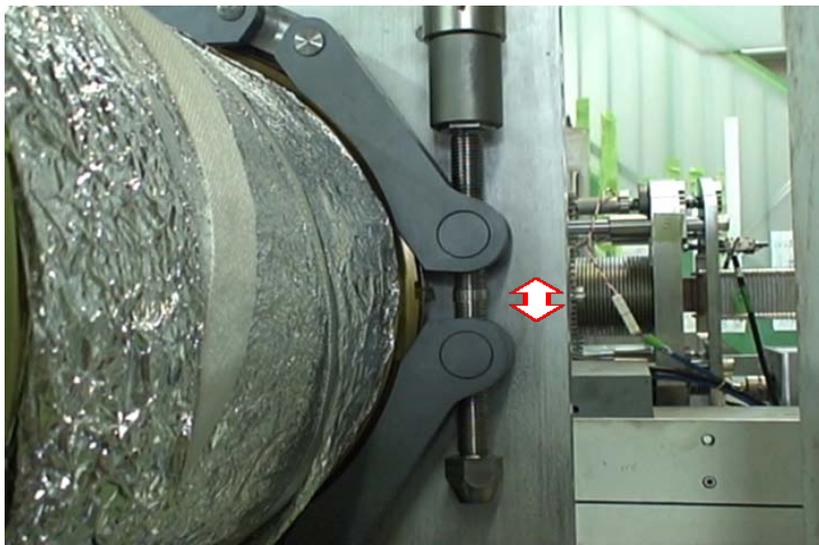




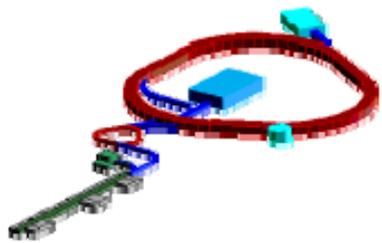
Remote clamp system



quick-clamp
closing screws



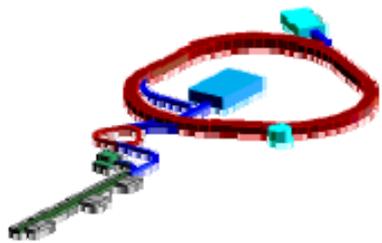
Fourth step : The nutrunner control the closing torque of quick-coupling clamp.



Inside of the beam collimator shielding.



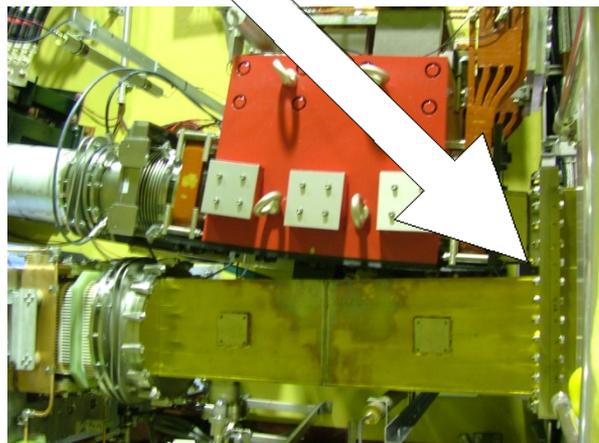
Inside of the collimator chamber.
4 absorbers were coated with TiN.



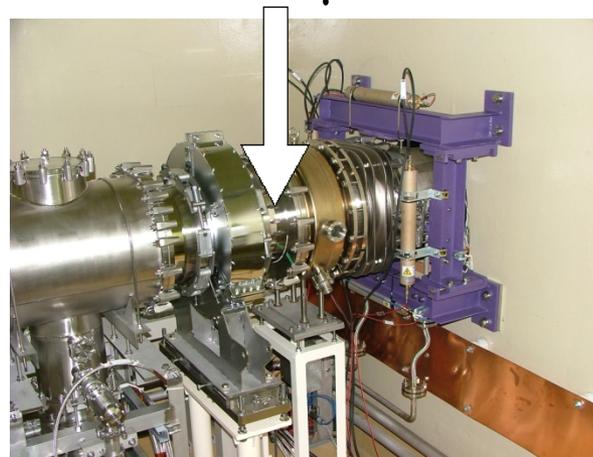
12/7 再測定①



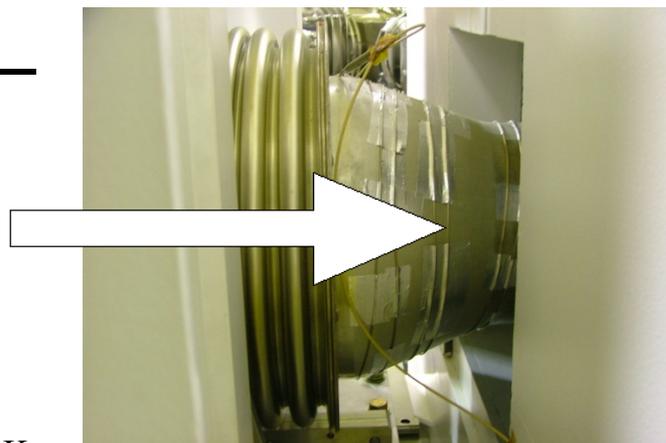
入射合流ダクト股部分
10 μ Sv以下

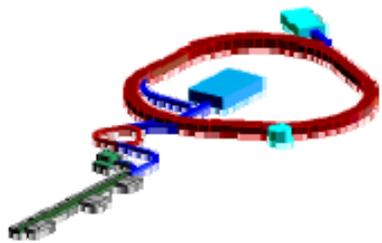


PPS-CT下流側
25~30 μ Sv(上下左右)



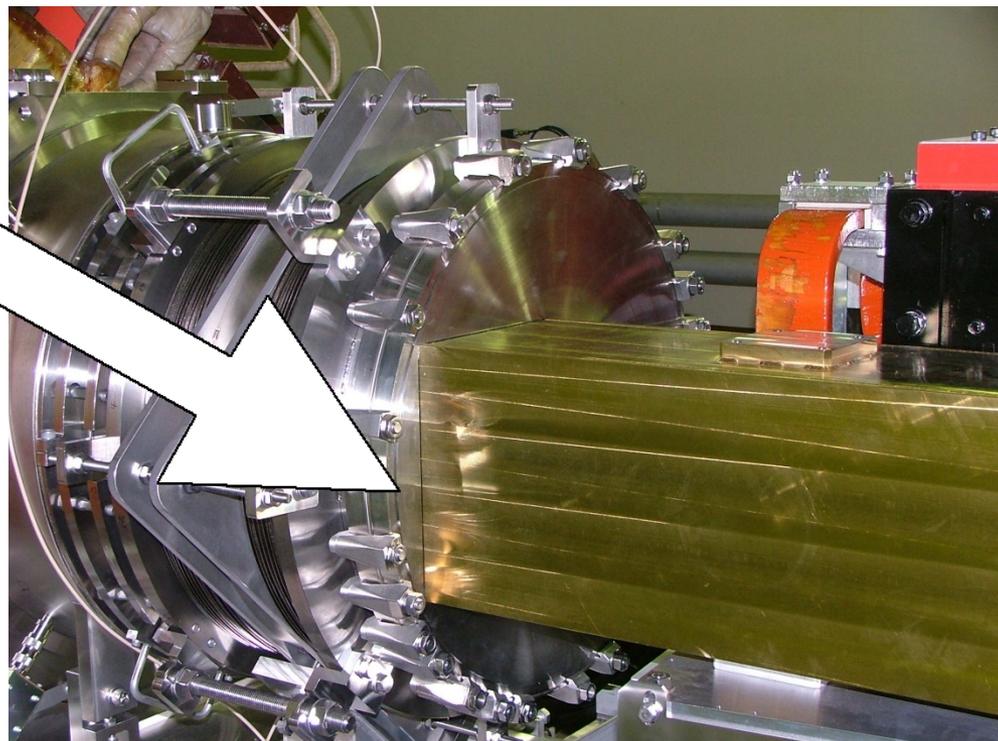
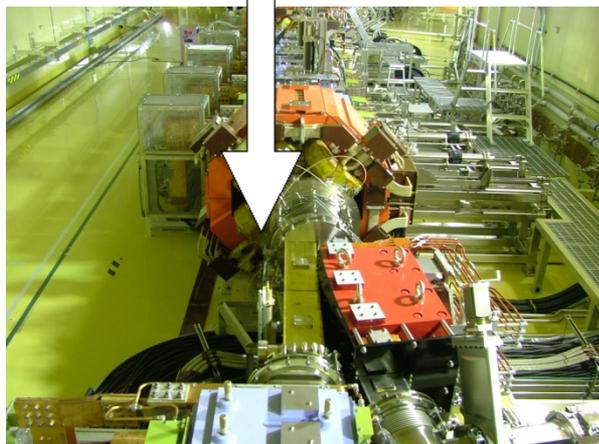
コリメータ先頭チャンバー
内周: 30 μ Sv
外周: 100 μ Sv
上下: ~15 μ Sv

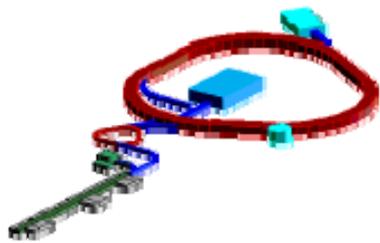




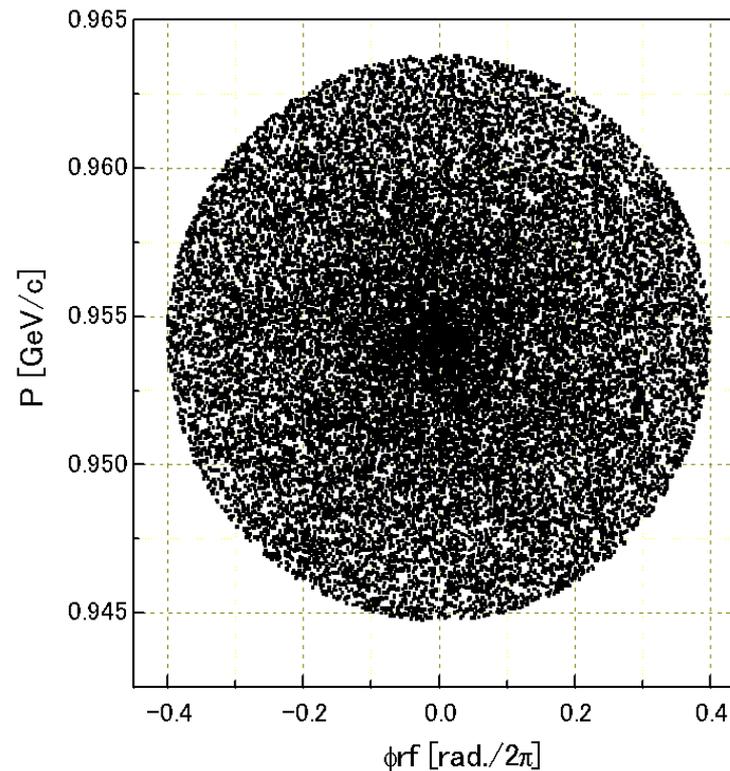
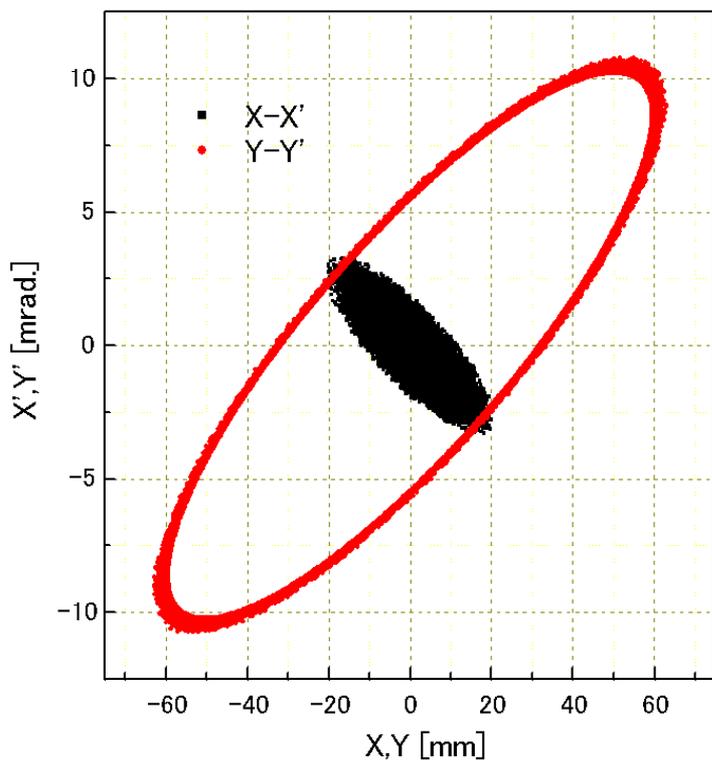
12/7 再測定②

H0ダンプ分岐チャンバー
内周 : $20\mu\text{Sv}$
上下外周
: $\sim 10\mu\text{Sv}$



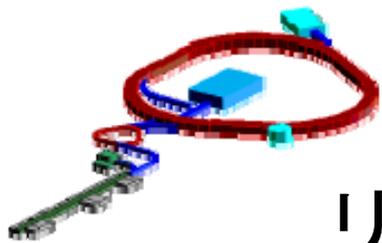


トラッキング初期条件



●ビームハロー

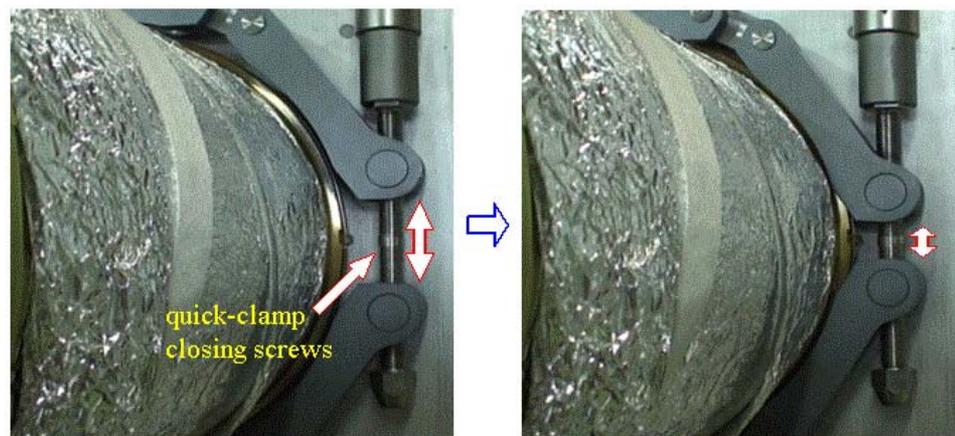
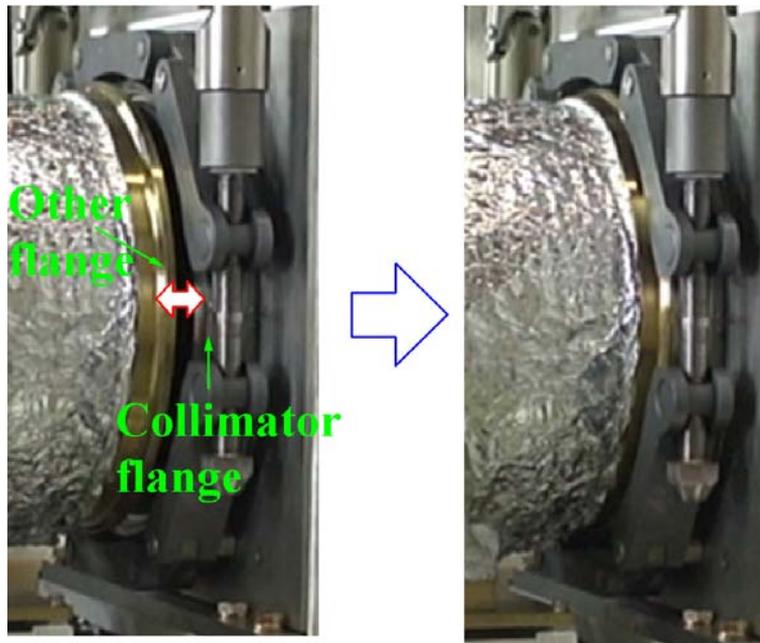
Transverse: $344 > \varepsilon_{x,y} > 324 \pi$ mm-mrad. 4
k Wを仮定



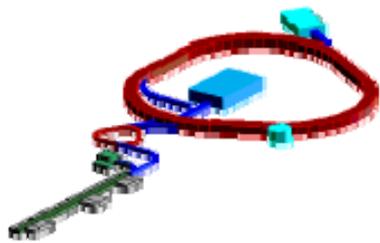
リモートクランプシステムの開発②

○フランジ接続動作

○クランプ締結動作



作業精度を考慮して、フランジ面間が1mmずらした状態での取り付け
→フランジ内部に取り付けられたガイドによって接続時に修正。 $5.0 \times 10^{-11} \text{Pa} \cdot \text{m}^3/\text{sec}$ 以下のリーク量で締結可能



ガンマ線照射試験



日本原子力研究開発機構 高崎量子応用研究所のガンマ線照射施設 第1照射棟Co60線源を用いた γ 線照射試験

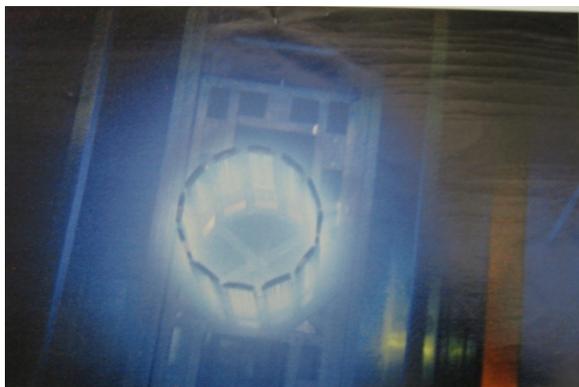


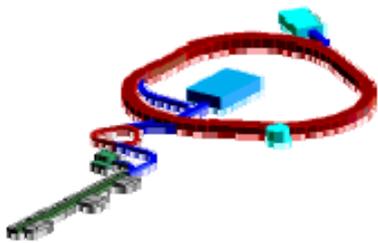
コリメータで使用する機器の耐放射線量

MARSでの評価→100MSv以上

γ 線換算で100MGy以上を目標

照射線量は、アラニン線量計中のラジカル量を電子スピン共鳴 (ESR) スペクトルで測定することで求められる。





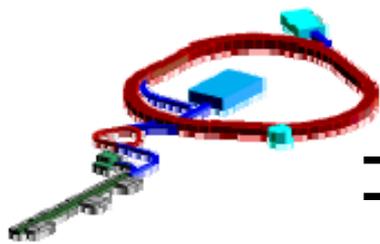
コリメータの真空処理

加速器での真空の必要性

- ・残留ガスとの衝突を繰り返すことによるビームロス
- ・それらビームロスやイオン化した残留ガスが真空容器表面に衝突し、壁面からガスが放出されさらなる真空度の悪化
- ・真空度が悪いと真空機器の寿命を縮めメンテナンスの頻度が上昇
- ・残留ガスのイオン化によって発生した電子が増幅し不安定性が発生



**コリメータブロックの高温真空脱ガス処理
表面へのTiNコーティングとその特性試験**



ポリメータ銅ブロックのプリベーク

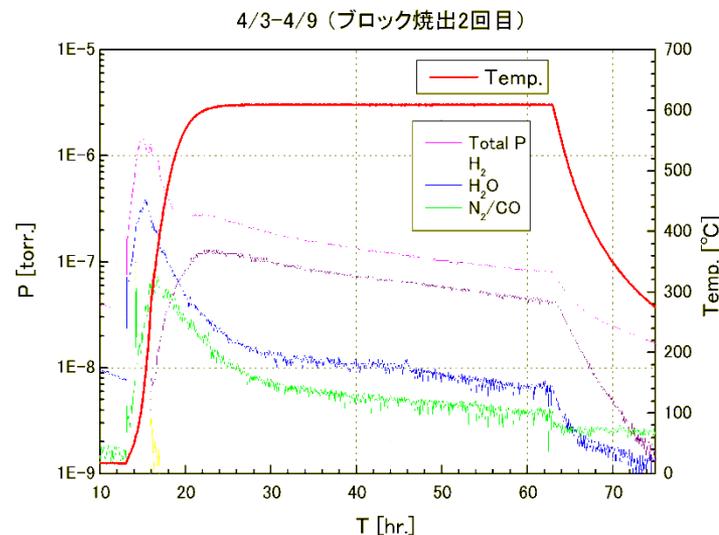
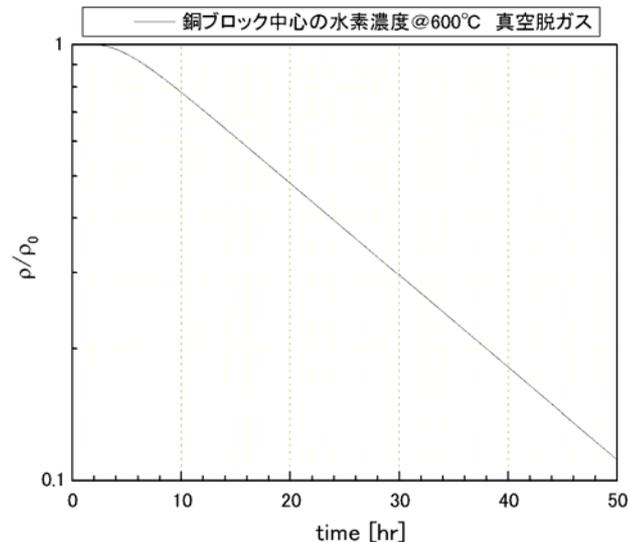


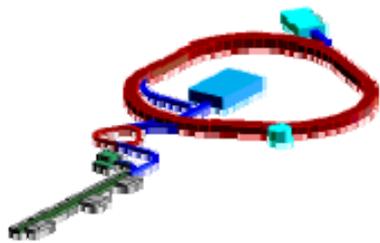
バルク中のガス成分の除去を行い、ビーム衝撃による真空度悪化を抑制



目標:バルク中の水素濃度を1/10以下に低減

焼き出し条件
:600°C 40時間キープ





残留線量②

●メンテナンス作業時の被曝線量の
 詳細検討
 (PHITS, DCHAIN-SP, QAD-CGGP2
 codes)

●400MeV, 1.2kW loss @
 一台目のセカンダリーコリメータ

●1年ビーム照射/1週間冷却後の結果

No.1 : 15.9mSv/hr.

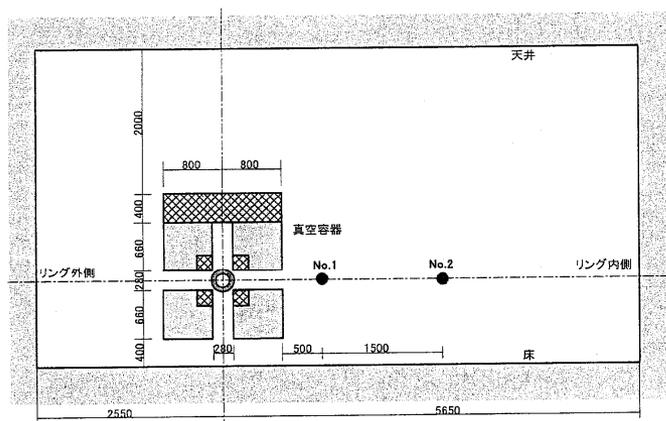
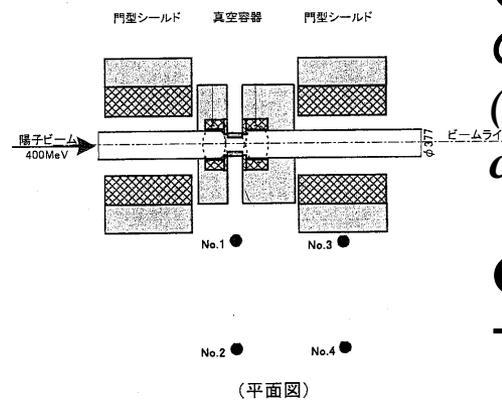
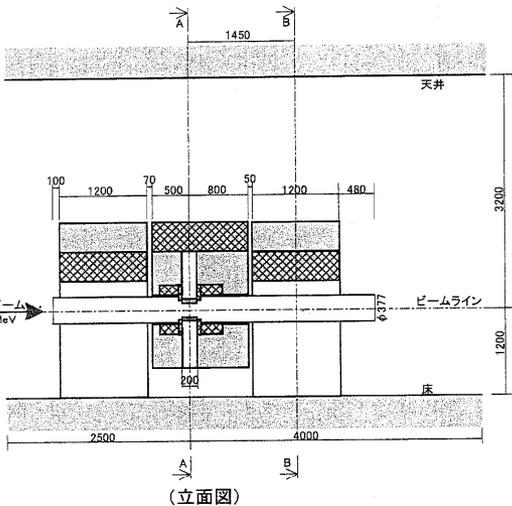
No.2 : 2.78mSv/hr.

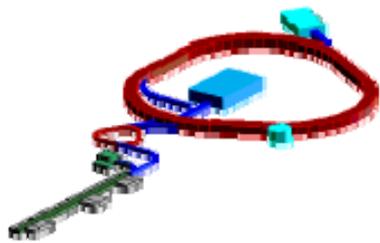
No.3 : 36.5μSv/hr.

No.4 : 189μSv/hr.

遮蔽体の影であれば

Hands-on maintenance可能





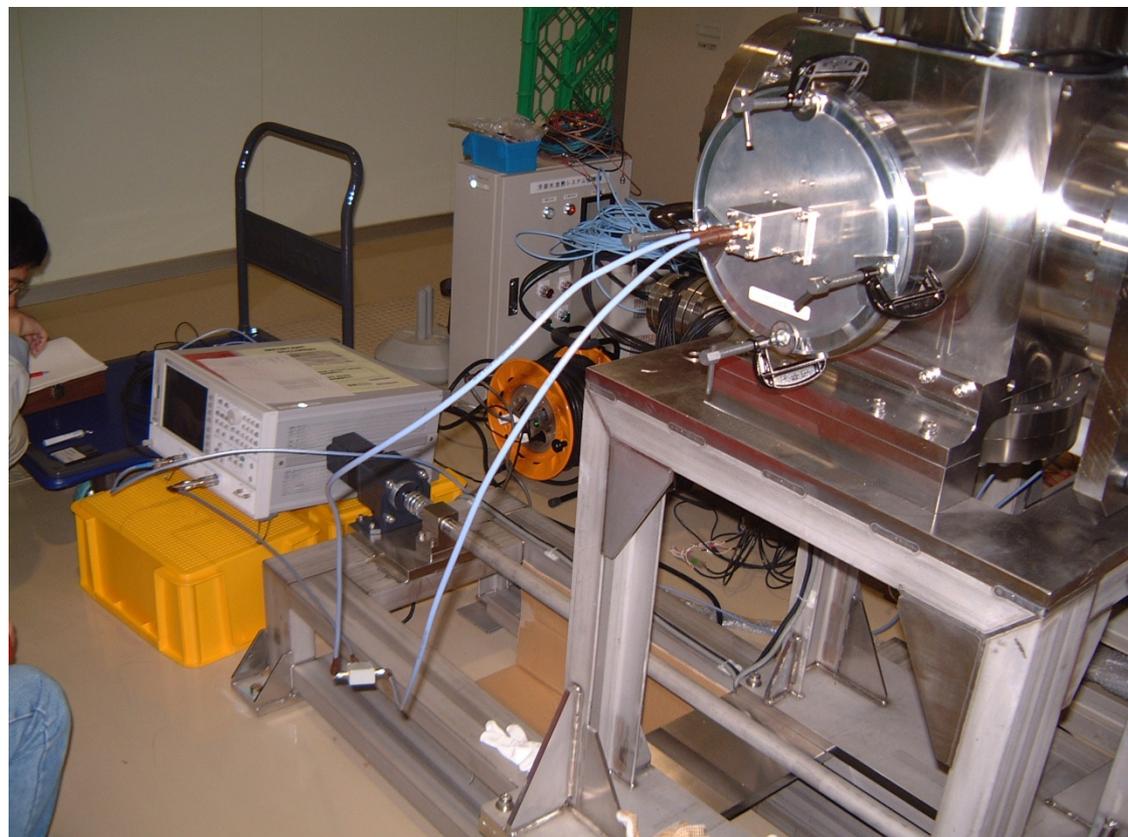
インピーダンス測定

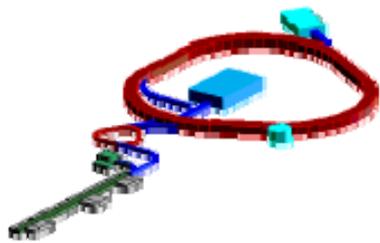
● 試作コリメータにて、
縦方向インピーダンス
をワイヤー法にて測定

$$\frac{Z_L}{n} \approx 0.20 \quad \Omega @ \textit{Injection}$$
$$\approx 0.28 \quad \Omega @ \textit{Extraction}$$

↓

Criteria 1071Ω@Injection
40Ω@Extraction
はクリアーする事を確認





PBI

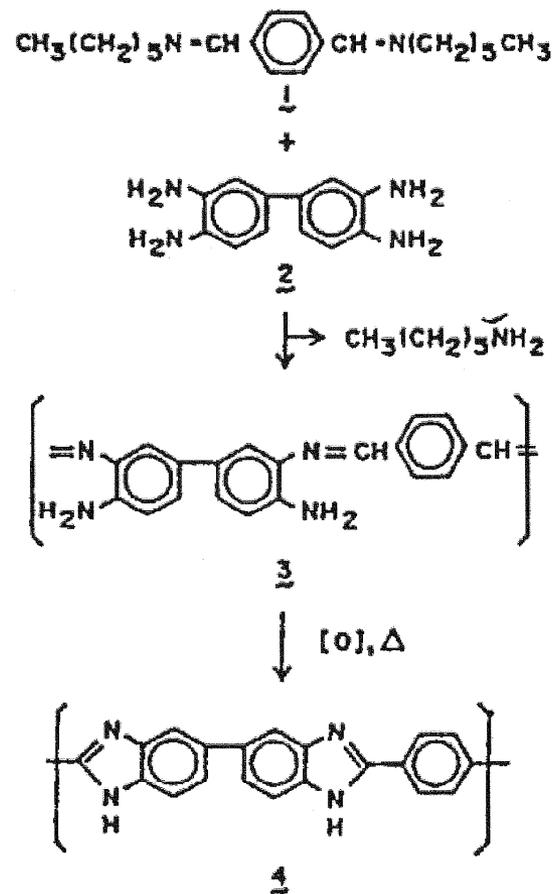
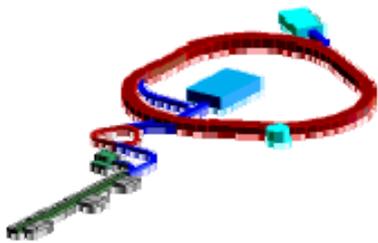
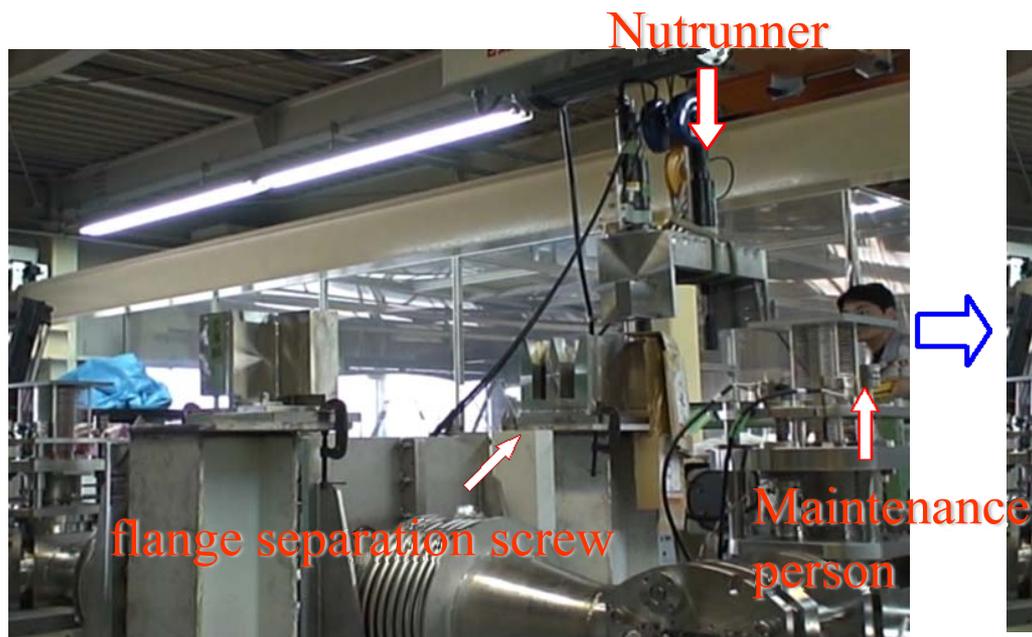


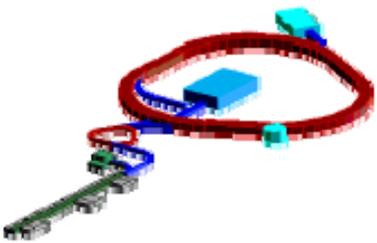
Fig.2. Synthesis of aromatic polybenzimidazole (PBI).



Remote clamp system ②

First step : We set the nutrunner on the flange separation screw from several meter away from the collimator chamber.





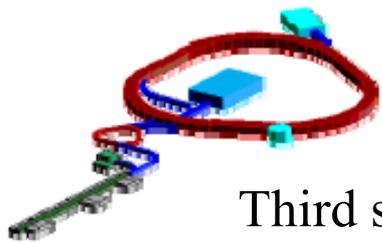
Remote clamp system



③

Second step : The nutrunner close the separation of each flange.



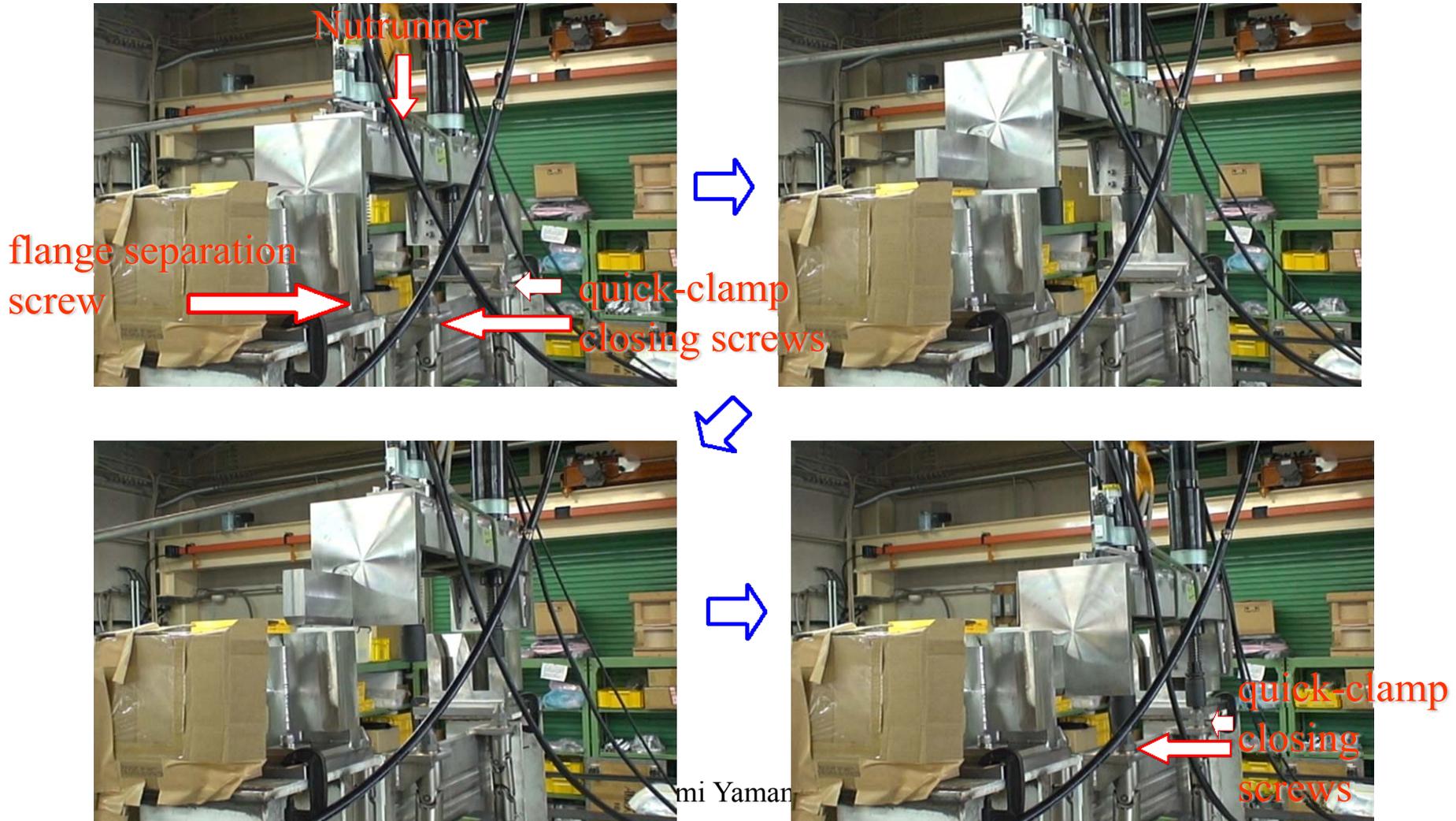


Remote clamp system

④



Third step : The nutrunner is remounted from the flange separation screw to the quick-clamp closing screws.

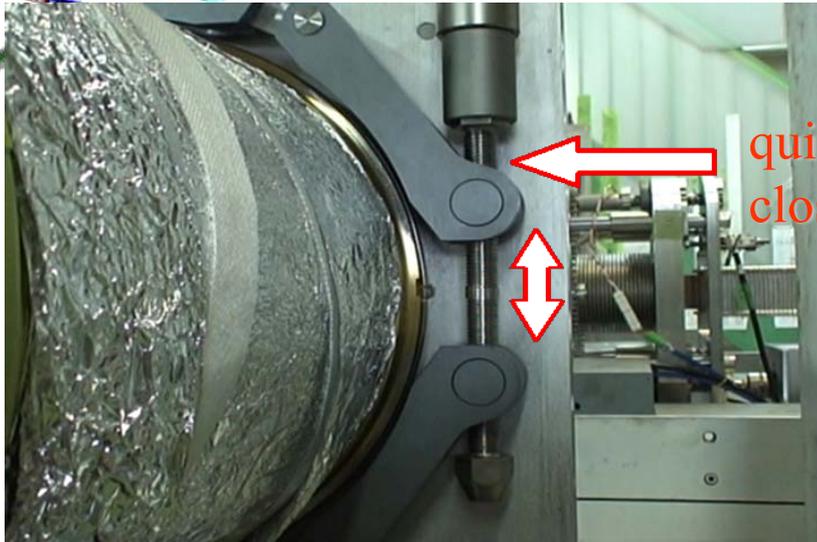




Remote clamp system



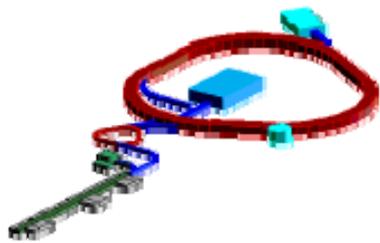
⑤



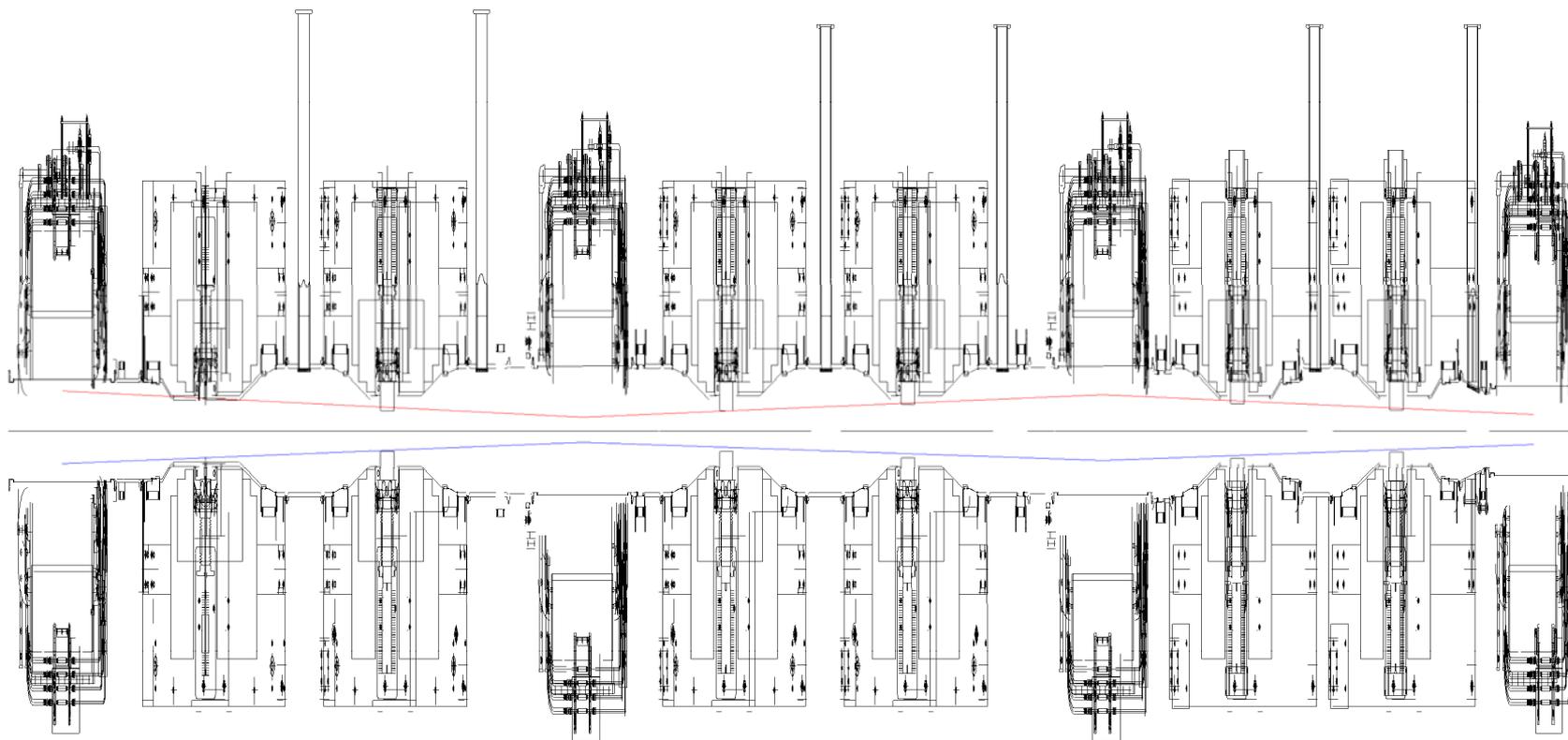
quick-clamp
closing screws

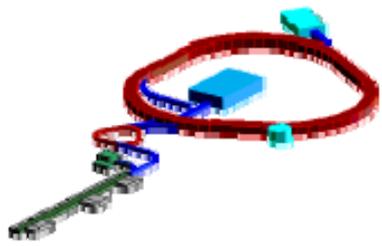


Fourth step : The nutrunner
control the closing torque of
quick-coupling clamp.

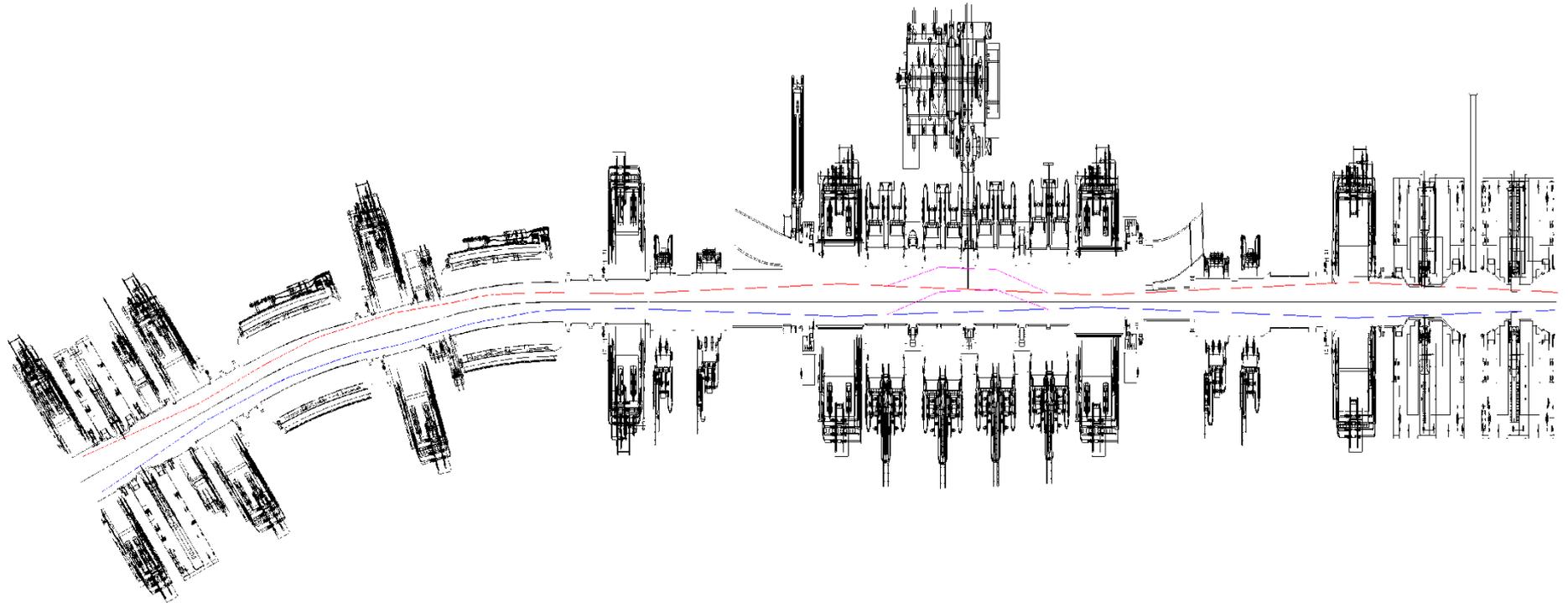


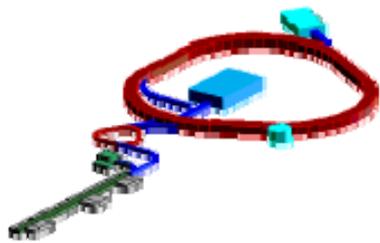
ビームエンベロープ①





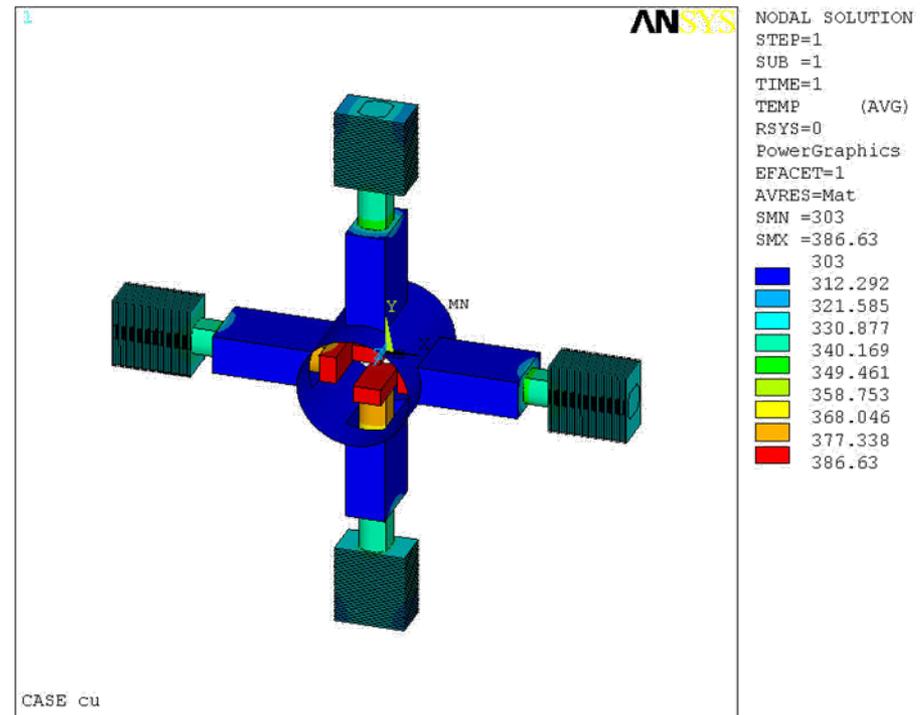
ビームエンベロープ②





冷却機構の検討②

- ・銅ブロックサポートアームを太くしてヒートシンクとし、外に逃がす方式を検討
- ・ANSYS を用いて、サポートアームの熱伝導による冷却効率の評価
- ・サポートアームを $\phi 140$ mm以上の太さにすれば、最大入熱量700 Wでも温度は 150°C 以下に保たれる。



ANSYS計算結果



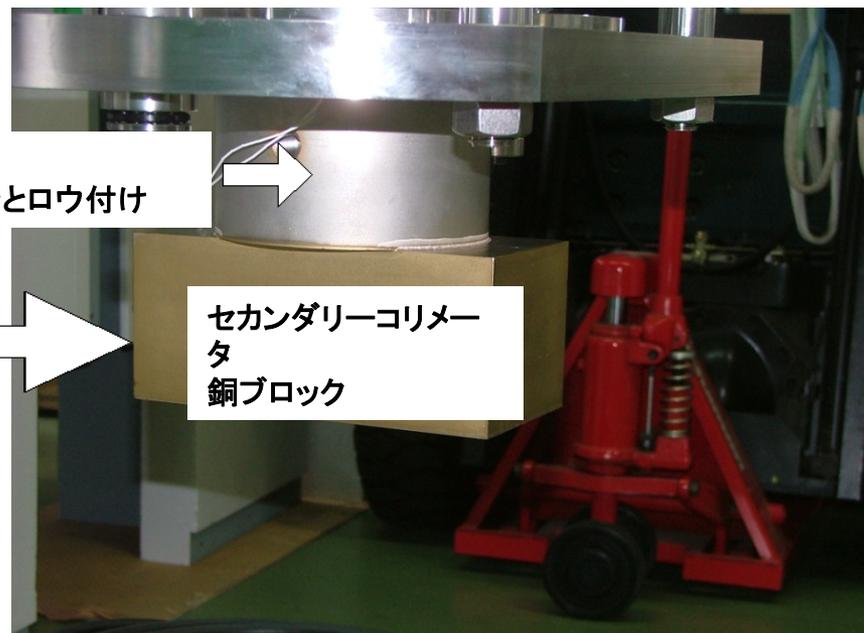
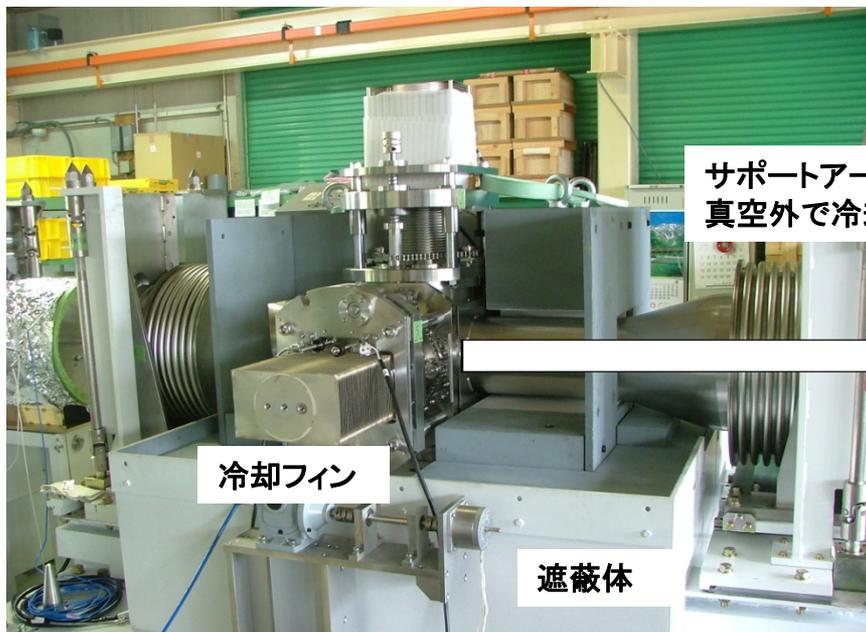
冷却機構の検討③



●試作機で試験を行った結果、遮蔽体に覆われた状態でも400 Wまでであれば最大温度が130°C以下に抑えられる。また、強制空冷を行なえば、700 Wの入熱でも120°C以下に抑えられる事が判明

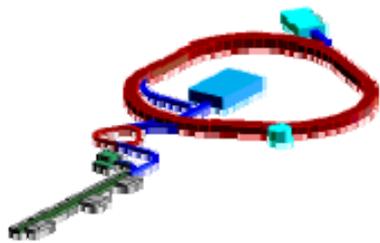


温度が高くなると見込まれる場所には、強制空冷用のエアダクトを追加、遮蔽体外より空気を送り込む事ができるように修正。→**ブロックを150°C以下に保持可能**



コリメータ真空容器と下部遮蔽体

真空容器内コリメータブロック



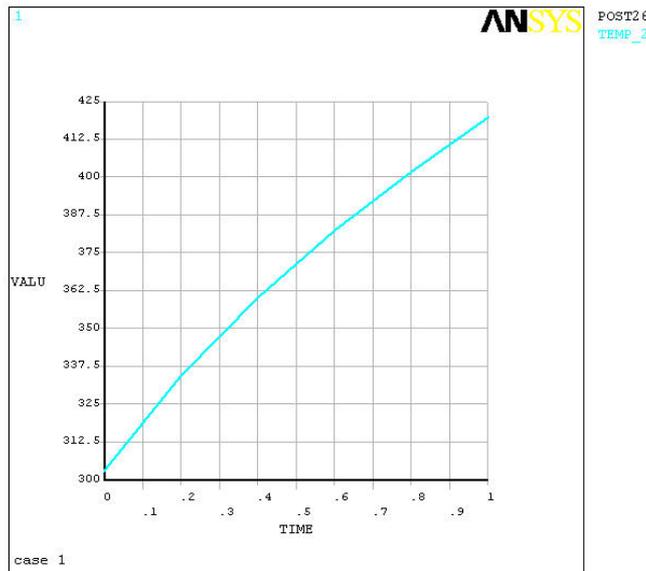
冷却機構の検討④



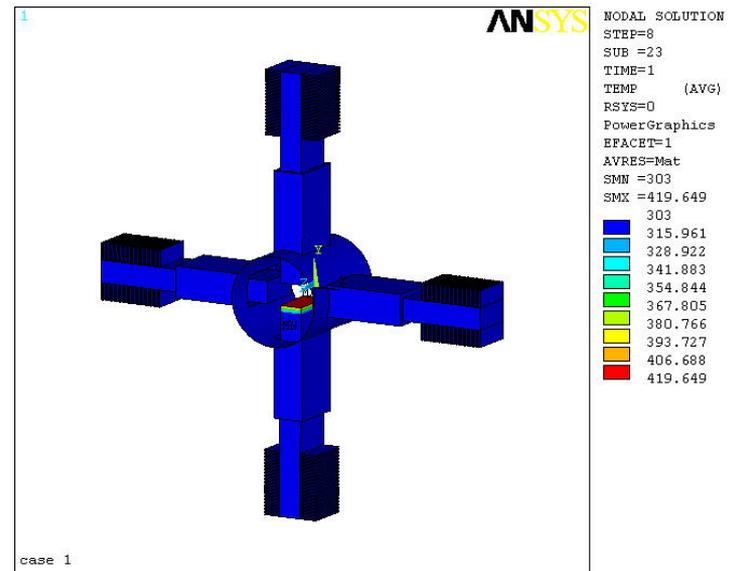
何らかの故障が発生しフルビームロスが生じた場合

→1秒間フルビームが照射しても、温度上昇は420 K程度。

実際は、MPSによって1パルスのフルビームロスが発生した時点でビームを停止



ANSYS計算結果①



ANSYS計算結果②